

Linear Actuator LA37

User Manual



Contents

Preface	3
Terms of use	4
Introduction	5
Safety instructions	5
Features	7
Options in general	8
Usage	9
Ordering example	10
Speed and current curves	13
Speed and current curves	14
Speed and current curves	15
The current limiting algorithm	16
Current limits	17
Max. current	17
Current cut-offs	18
Mounting guidelines	19
Built-in dimensions	21
Keep a clearance when mounting a bracket	21
Built-in dimensions For Shot BID option	23
Cable mounting	24
Mounting of cable Off-highway	25
Off-highway connection to Actuator Connect™	26
Electrical installation	26
Manual hand crank	27
Label for LA37	28
Declarations of Conformity	29
Contacts	37

Preface

Dear User,

We are delighted that you have chosen a LINAK® product.

LINAK systems are high-tech products based on many years of experience in the manufacture and development of actuators, lifting columns, desk frames, electric control boxes, controls, batteries, accessories and chargers.

This User Manual does not address the end user. It is intended as a source of information for the equipment or system manufacturer only, and it will tell you how to install, use and maintain your LINAK electronics. The manufacturer of the end product has the responsibility to provide a User Manual, where relevant safety information from this manual is passed on to the end user.

We are convinced that your LINAK product/system will give you many years of problem-free operation.

Before our products leave the factory, they undergo both function and quality testing. Should you, nevertheless, experience problems with your product/system, you are always welcome to contact your supplier.

LINAK subsidiaries and some distributors situated all over the world have authorised service centres, which are always ready to help you. Locate your local contact information on the back page.

LINAK provides a warranty on all products. (See warranty section).

This warranty, however, is subject to correct use in accordance with the specifications, maintenance being done correctly, and any repairs being carried out at a service centre, which is authorised to repair LINAK products.

Changes in installation and use of LINAK systems can affect their operation and durability. The products may only be opened by authorised personnel.

This User Manual has been written based on the present technical knowledge. LINAK reserves the right to carry out technical modifications and keeps the associated information updated.

LINAK A/S



Terms of use

LINAK® takes great care in providing accurate and up-to-date information on its products. However, the user is responsible for determining the suitability of LINAK products for a specific application.

Due to continual development, LINAK products are subject to frequent modifications and changes. LINAK reserves the rights to conduct modifications, updates, and changes without any prior notice. For the same reason, LINAK cannot guarantee the correctness and actual status of imprinted information on its products.

LINAK uses its best efforts to fulfil orders. However, for the reasons mentioned above, LINAK cannot guarantee availability of any particular product at any given time. LINAK reserves the right to discontinue the sale of any product displayed on its website or listed in its catalogues or in other written material created and produced by LINAK, LINAK subsidiaries, or LINAK affiliates.

All sales are subject to the 'Standard Terms of Sale and Delivery for LINAK A/S' available on LINAK websites.

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Introduction

Powerful electric linear actuator designed to handle high loads and demanding environments. It delivers long-lasting reliability as well as a wide choice of industrial control interfaces.

Safety instructions

Please read this safety information carefully.

Be aware of the following three symbols throughout the document:



Warning!

Failing to follow these instructions can cause accidents resulting in serious personal injury.



Recommendations

Failing to follow these instructions can result in the actuator suffering damage or being ruined.



Additional information

Usage tips or additional information that is important in connection with the use of the actuator.

Furthermore, ensure that all staff who are to connect, mount, or use the actuator are in possession of the necessary information and that they have access to this document.

Persons who do not have the necessary experience or knowledge of the product/products must not use the product/products. Besides, persons with reduced physical or mental abilities must not use the product/products, unless they are under surveillance or they have been thoroughly instructed in the use of the apparatus by a person who is responsible for the safety of these persons.

Moreover, children must be under surveillance to ensure that they do not play with the product.

Before you start mounting/dismounting, ensure that the following points are observed:

- The actuator is not in operation.
- The actuator is free from loads that could be released during this work.

Before you put the actuator into operation, check the following:

- The actuator is correctly mounted as indicated in the relevant user instructions.
- The equipment can be freely moved over the actuator's whole working area.
- The actuator is connected to a mains electricity supply/transformer with the correct voltage which is dimensioned and adapted to the actuator in question.
- Ensure that the voltage applied matches to the voltage specified on the actuator label.
- Ensure that the connection bolts can withstand the wear.
- Ensure that the connection bolts are secured safely.

During operation, please be aware of the following:

- Listen for unusual sounds and watch out for uneven running. Stop the actuator immediately if anything unusual is observed.
- Do not sideload the actuator.
- Only use the actuator within the specified working limits.
- Do not step on or kick the actuator.

When the equipment is not in use:

- Switch off the mains supply in order to prevent unintentional operation.
- Check regularly for extraordinary wear.

Classification

The equipment is not suitable for use in the presence of a flammable anaesthetic mixture with air or with oxygen or nitrous oxide.

**Warnings**

- Do not sideload the actuator.
- When mounting the actuator in the application ensure that the bolts can withstand the wear and that they are secured safely.
- If irregularities are observed, the actuator must be replaced.
- The standard actuator (without Integrated Controller) without clutch, is not allowed to run into a mechanical block -before reaching the end of stroke.

**Recommendations**

- Do not place load on the actuator housing.
- Prevent impact or blows, or any other form of stress to the housing.
- Ensure that the cable cover is mounted correctly. Use 3.5 Nm torque.
- Ensure that the duty cycle and the usage temperatures for LA37 actuators are respected.
- Ensure that the cable cannot be squeezed, pulled or subjected to any other stress.
- Furthermore, it will be good practice to ensure that the actuator is fully retracted in the "normal" position. The reason is that there will be a vacuum inside the actuator if it is extended which over time can lead to water entering the actuator.

Features

- 12 / 24 / 48 V DC Brushed motor permanent magnetic motor
- Load from 10,000 N - 15,000 N
- Max. speed 10 mm/sec. depending on load and spindle pitch
- Stroke length from 100 mm to 600 mm (601 -1,000 mm as special item)
- Built-in endstops reached function
- Highly efficient acme thread spindle
- Heavy duty aluminium housing for harsh conditions
- Protection class: IP66 for outdoor use (dynamic). Furthermore, the actuator can be washed down by a high pressure cleaner (IP69K - static)
- Highly efficient acme thread spindle
- Static holding load up to 45 kN in push and pull
- Dynamic wind stress loads 15 kN push/pull 100,000 times
- Hand crank for manual operation
- Integrated brake, high self-lock ability
- Endplay - See [Technical Specifications](#)
- Non-rotating piston rod eye
- Noise level: 76 dB (A). Measuring method: DS/EN ISO 8746 (actuator not loaded)
- Current monitoring
- Off-highway Features:
 - 12 or 24 V DC brushed permanent magnetic motor
 - Load up to 15,000 N (depending on the spindle pitch)
 - Max. speed 10 mm/sec.
 - Reinforced aluminium housing for harsh conditions
 - IPC-A-610 Class 3 (High-performance electronic products)
 - IP54 without cable mounted
IP69K with cable mounted with shell or moulded cable

An Off-highway vehicle is intended for use on steep or uneven ground and includes those used for construction or agriculture. They are specifically designed for off-road use.

Quad bikes, dirt bikes, dune buggies and other types of all-terrain vehicles are also types of Off-highway vehicles, although their function is very different from motor vehicles designed for industrial and farming use.



For more information about I/O, please see the [I/O interface user manual](#)

Options in general

- Back fixture can be ordered in steps of 90 degrees
- Exchangeable cables in different lengths
- Hall effect sensor
- Analogue or digital feedback for precise positioning
- Different back fixtures and piston rod eyes
- Endstop reached signals
- Built-in Zero Point or endstop switch initialisation principle
- IC options including:
 - I/O
 - Ethernet/IP
 - Modbus TCP/IP
 - Modbus RTU
 - IO-Link
 - LIN bus
 - CAN SAE J1939
 - CANopen
 - Off-highway LIN bus (contact LINAK sales)
 - Off-highway CAN SAE J1939
 - Off-highway CANopen

(see specific interface user manuals at the [TECHLINE webpage](#) for Connection Diagrams and I/O Specifications)

- PC configuration tool (Actuator Connect™ and BusLink)

Ordering example**37 080 200 0 A 01 B 6 - 6 1 2 H 3 XXXX A C S 0 0 0**

Actuator type	37 = LA37		
Spindle type	025 = 2.5 mm	080 = 8 mm	
Stroke length	200 = XXX Length in mm (50-999)	A00 = 1000 Length in mm	
Safety	0 = No safety nut		
Feedback	0 = No Feedback A = Hall Potentiometer H = Dual Hall	9 = Hall Potentiometer, 2-wire K = Single Hall X = Special	
Platform	6-pin	9-pin	
	Endstop switch principle	Zero Point	
See Current limits and Current cut-offs for availability of voltage	01 = Standard with power switch 04 = Modbus 06 = LIN bus 07 = CAN SAE J1939 08 = CANopen	B3 = I/O Basic C3 = I/O Customised F3 = I/O Full 0B = IO-Link 14 = Modbus RTU	
	Zero Point	Zero Point with split supply	
	16 = LIN bus 17 = CAN SAE J1939 18 = CANopen	A7 = CAN SAE J1939 A8 = CANopen 0E = Modbus TCP/IP 2E = Ethernet/IP 4E = Profinet	
	18-pin Off-highway		
	C6* = LIN bus ** D6* = CAN SAE J1939 E6* = CANopen XX = Special		
Motor type	1 = 12 V DC 2 = 24 V DC 3 = 48 V DC		

* Requires Housing option 'C' IP66 Off-highway, also only available with Motor Type 1 or 2

** Please contact LINAK for further information

Housing	6	= IP66 - Reinforced house	C*	= IP54 - Off-highway house
Not used	-	= Not used		
Colour	6	= Dark Olivish Grey NCS S7000-N		
Back fixture	1	= 0°	X	= Special
	2	= 90°		
Piston rod eye	2	= Solid	6	= Ball eye
	4	= Male Adapter (Outer thread)	X	= Special
Gear	H	= Ratio 1:46		
Brake	3	= Push/Pull		
Built-in dimension	xxxx	= Measured in mm		
Endstop reached output	A	= A_HIGH / A_HIGH	J	= A_HIGH / LOW
	B	= A_LOW / A_HIGH	K	= A_LOW / LOW
	C	= A_HIGH / A_LOW	L	= A_HIGH / HIGH
	D	= A_LOW / A_LOW	M	= A_LOW / HIGH
	E	= LOW / A_HIGH	N***	= LOW / LOW
	F	= HIGH / A_HIGH	O	= HIGH / LOW
	G	= LOW / A_LOW	P	= LOW / HIGH
	H	= HIGH / A_LOW	Q	= HIGH / HIGH
			X	= Special
Plug type	0**	= No plug (when no cable is chosen)	H	= AMP
	J	= Deutsch	K	= AMP Super Seal
	9	= Deutsch - Moulded	7	= AMP Super Seal - Moulded
	C	= Flying leads	E	= M12 Y Ethernet/IP
	N	= M12 IO-Link	R	= M12 Modbus
			X	= Special
Cable	0**	= No cable selected	A	= Mounted with 90° angled connectors
	S	= Straight cable	Y	= Y-Cable (combined power and signal cable)
			X	= Special

* Requires Platform option 18-pin Off-highway - Only available with Motor Type 1 or 2

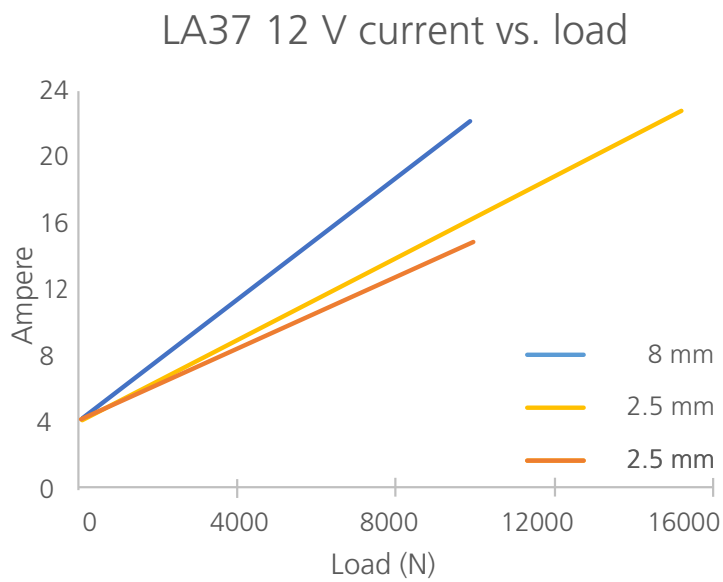
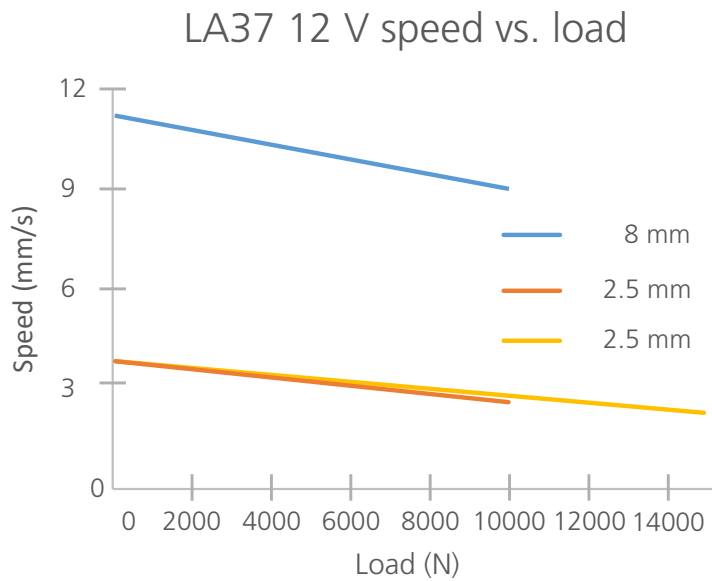
** Shall be chosen with 'Off-highway'

*** Mandatory for CAN SAE J1939, CANopen, LIN bus, Modbus and IO-Link

Parallel mode	0 = The system is NOT parallel	2-8 = Critical parallel (number of actuators in the parallel system)
SW config.	0 = Standard software	X = Special software
Short BID	0 = Standard	A* = Short (conform with LA36)
*	Only optional with Spindle type 080	

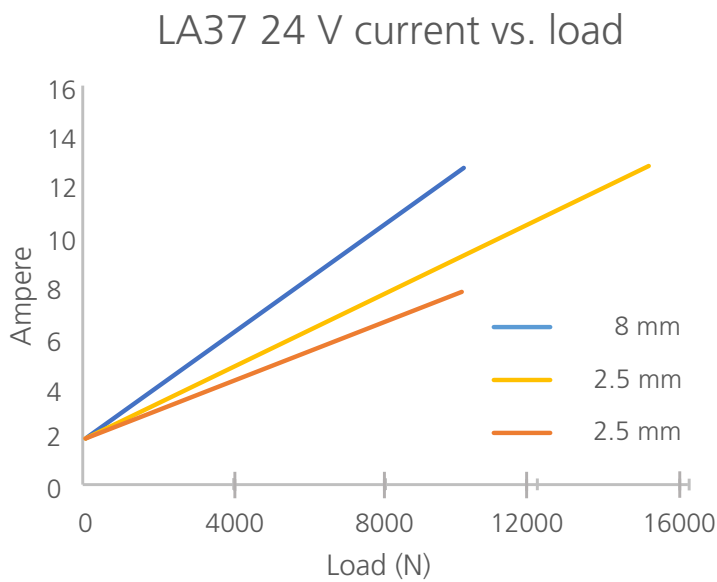
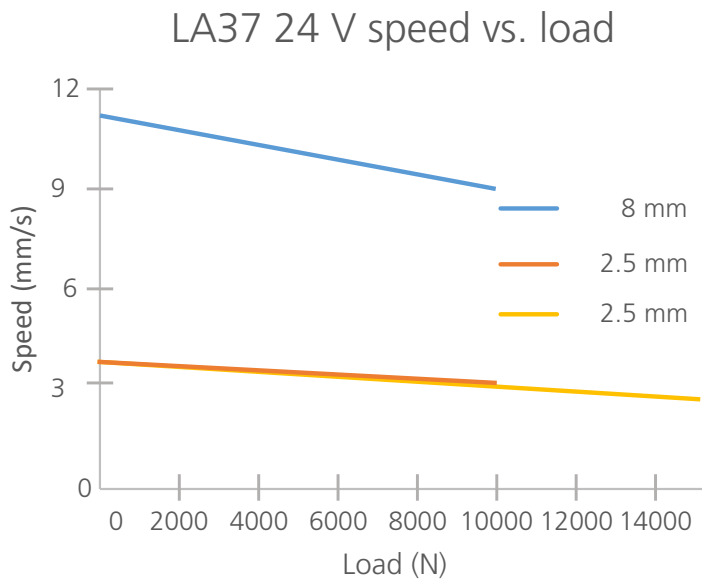
Speed and current curves

The typical values below are made with a nominal power supply of 12 V DC and an ambient temperature of 20°C.



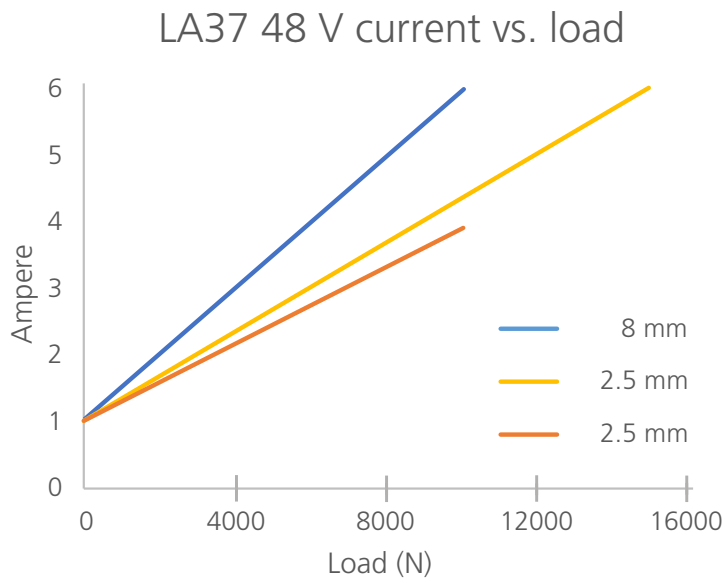
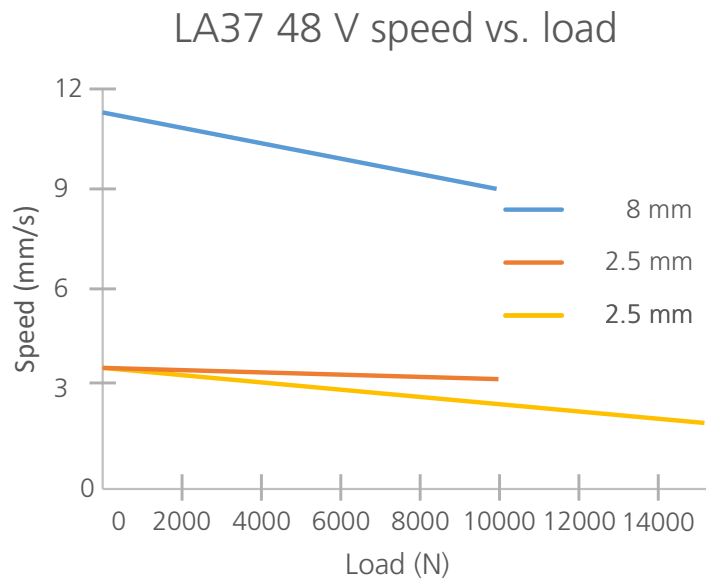
Speed and current curves

The typical values below are made with a nominal power supply of 24 V DC and an ambient temperature of 20°C.



Speed and current curves

The typical values below are made with a nominal power supply of 48 V DC and an ambient temperature of 20°C.



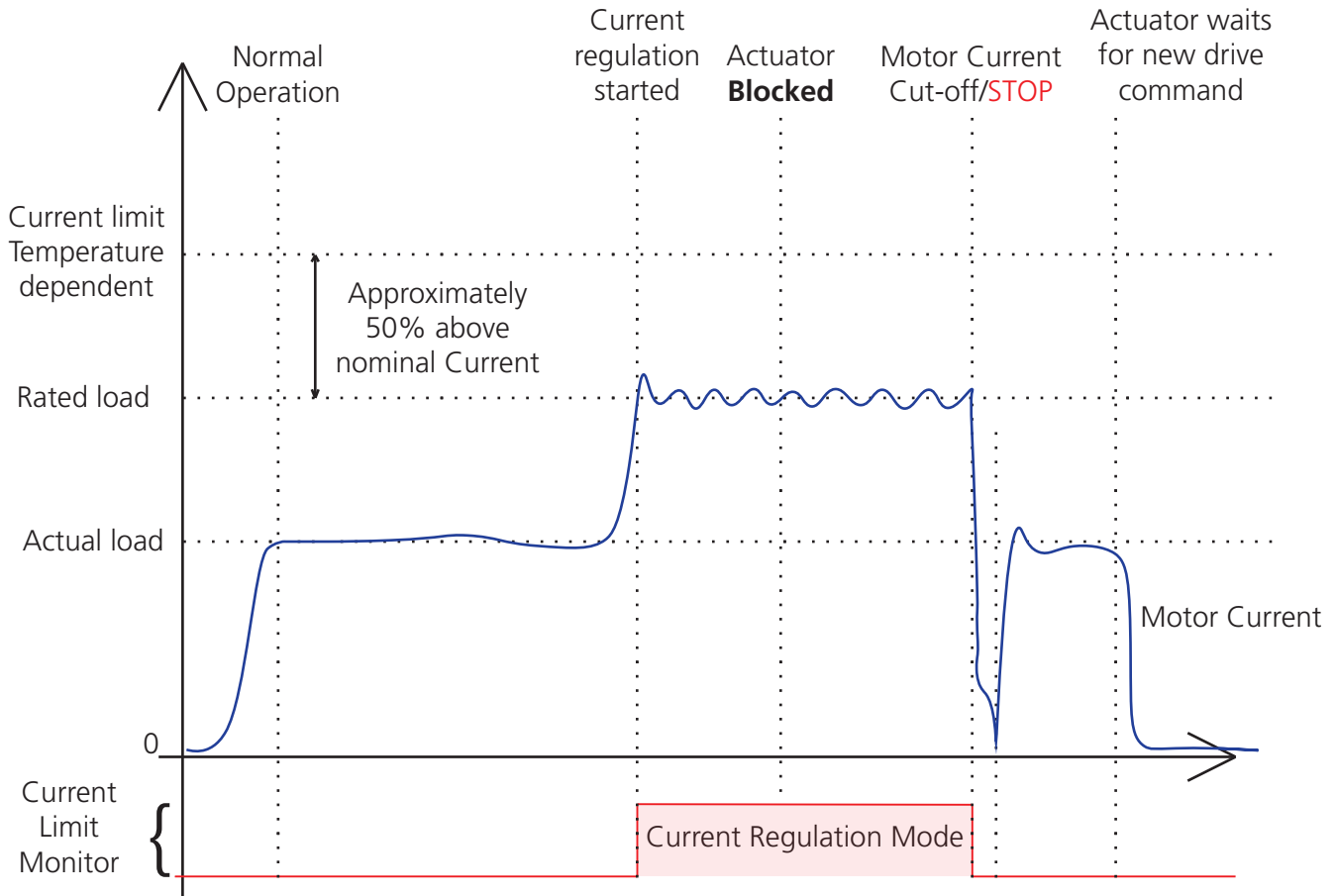
The current limiting algorithm

The I/O™ actuator features the latest current limiting algorithm, which has been significantly improved compared to previous versions.

If the actuator's current consumption rises above the set limit, the actuator regulates and tries to keep it below the set current limit by reducing the PWM and therefore also the speed accordingly. The actuator does this continuously, until the actuator stops moving (mechanically blocked) - something that is determined by monitoring the Hall feedback signal. If there are no changes to the Hall feedback signal during the set time frame, the integrated controller will cut power to the H-bridge motor circuit.

If the actuator is stopped due to the above-mentioned criteria, it automatically drives slightly in the opposite direction to reduce the torque in a blocking situation.

This is visualised in the figure below:



This control feature makes it possible to avoid loading the internal mechanical system of the actuator above its specification, which ultimately means a longer life for the actuator, especially in an abuse scenario.



The I/O™ actuator comes with factory default current limits. These values can be customised with the 'Protection' option in Actuator Connect™ or when ordering the actuator.

Current limits

As described in the algorithm on previous page.

Platform		12 V	24 V	48 V	Reference temperature: 0°C
B3	I/O Basic	26 A	13 A	8 A	Above
C3	I/O Customised	26 A	26 A	13 A	Below
F3	I/O Full				
A6	LIN bus	-	13 A	8 A	Above
		-	26 A	13 A	Below
0B	IO-Link	-	16 A	-	Above
		-	26 A	-	Below
14	Modbus RTU	-	16 A	8 A	Above
		-	26 A	15 A	Below
C6	LIN bus Off-highway	26 A	13 A	-	Above
D6	CAN SAE J1939 Off-highway	26 A	26 A	-	Below
E6	CANopen Off-highway				

Platform		12 V	24 V	48 V	Reference temperature: 0°C
A7	CANbus J1939	-	13 A	8 A	Above
A8	CANopen	-	26 A	13 A	Below
0E	Modbus TCP/IP	-	16 A	8 A	Above
2E	Ethernet/IP	-	26 A	16 A	Below
4E	Profinet				

Max. current

The current is not limited by the actuator. Below is the anticipated consumption at max. load.
See: Recommended fuse for actuators without Integrated Controller.

Platform		12 V	24 V	48 V	Reference temperature: 0°C
01	Standard with power switch	26 A	13 A	8 A	Above
		26 A	13 A	8 A	Below

Current cut-offs

The principle behind the current cut-off measurement is an 'above limit' and a 'below limit' accumulating counter. When the time-out counter reaches a specific value the current cut-off goes into effect. The time-out value is pre-set at 200 ms.

Platform		12 V	24 V	48 V	Reference temperature: 0°C
04	Modbus	-	13 A	-	Above
		-	13 A	-	Below
06	LIN bus	30 A	-	-	Above
		30 A	-	-	Below
07 08	CAN SAE J1939 CANopen	30 A	20 A	-	Above
		30 A	25 A	-	Below

Platform		12 V	24 V	48 V	Reference temperature: 0°C
16	LIN bus	30 A	-	-	Above
		30 A	-	-	Below
17 18	CAN SAE J1939 CANopen	30 A	20 A	13 A	Above
		30 A	25 A	15 A	Below

Mounting guidelines

LINAK® linear actuators are quickly and easily mounted by slipping pins through the holes on each end of the units and into brackets on the machine frame and the load.

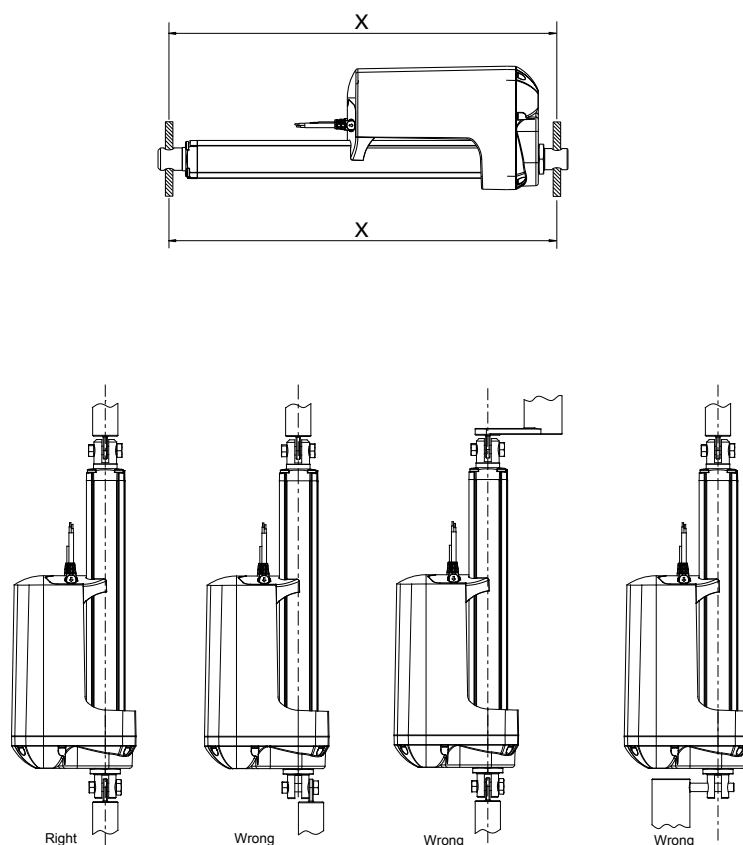
The mounting pins must be parallel to each other as shown in Figure 1. Pins, which are not parallel to each other, may cause the actuator to bend and be damaged.

The load should act along the stroke axis of the actuator since off centre loads may cause bending and lead to premature failure.

Make sure the mounting pins are supported in both ends. Failure to do so could shorten the life of the actuator. Cantilever mounts are unacceptable.

The actuator can rotate around the pivot point in the front and rear end. If this is the case, it is of high importance that the actuator is able to move freely over the full stroke length, both during the development and daily operation. Please pay special attention to the area around the housing where parts can be trapped and cause damages to the application and actuator.

In applications with high dynamic loads, LINAK recommends not to use the fully extended or retracted position over longer time, as this can damage the endstop system permanently.



Please be aware that if the LA37 is used for solar applications, the actuator must be mounted with the motor housing turned upwards and the wires pointing downwards.

Mounting guidelines



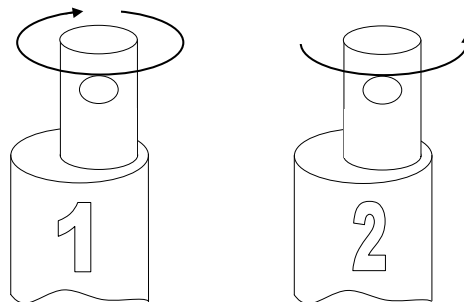
- The mounting pins must have the correct dimension.
- The bolts and nuts must be made of a high quality steel grade (e.g. 10.8). No thread on the bolt inside the back fixture or the piston rod eye.
- Bolts and nuts must be protected so there is no risk for them to fall out.
- Do not use a torque that is too high when mounting the bolts for the back fixture or the piston rod eye. This will stress the fixtures.

Please note: The piston rod eye is only allowed to turn 0-180 degrees.



Instruction concerning the turning of the piston rod eye and inner tube:

- When mounting and taking into use, it is not permitted to make excessive turns of the piston rod eye. In cases where the eye is not positioned correctly, it is permitted to first screw the eye down to its bottom position, at a maximum torque of 2 Nm (1), and thereafter a maximum 180 degrees turn out again (2).
- As the piston rod eye can turn freely, it is important to ensure that the eye cannot rotate if the actuator is used in a pull application. If this happens, the actuator will be pulled apart and destroyed.



Warning!

If the actuator is used for pull in an application where personal injury can occur, the following is valid:

It is the application manufacturer's responsibility to incorporate a suitable safety arrangement, which will prevent personal injury from occurring, if the actuator should fail.



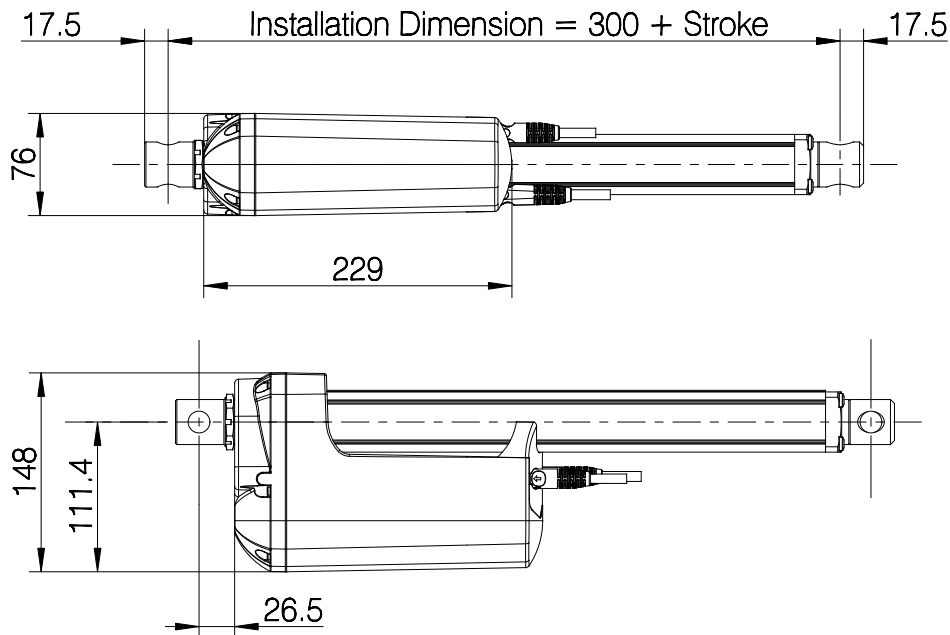
Warning!


LINAK® actuators are not designed for use within the following fields:

- Offshore installations
- Explosive environments
- Aeroplanes and other aircraft
- Nuclear power generation


Built-in dimensions

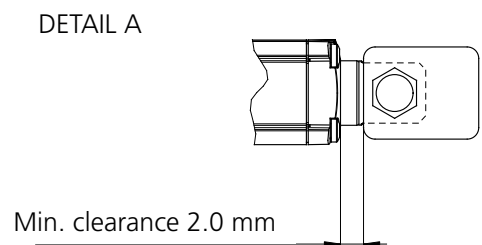
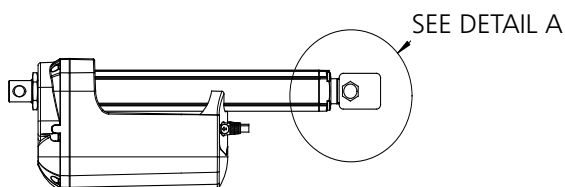
All dimensions are in mm



 The above dimensions apply for all LA37 piston rod eyes and back fixtures.

Keep a clearance when mounting a bracket

 When mounting a custom bracket on the moving part of the actuator, please observe the minimum clearance between bracket and cylinder top when fully retracted. This will prevent jamming and destruction of the actuator drive train.



With Zero Point the minimum stroke is 70 mm.
 The Zero Point initialisation zone is located between 35-70 mm going from the most inward position.
 The movement passing the zone has to be stable for the initialisation to succeed - also, no virtual limits can be set in the initialisation zone.

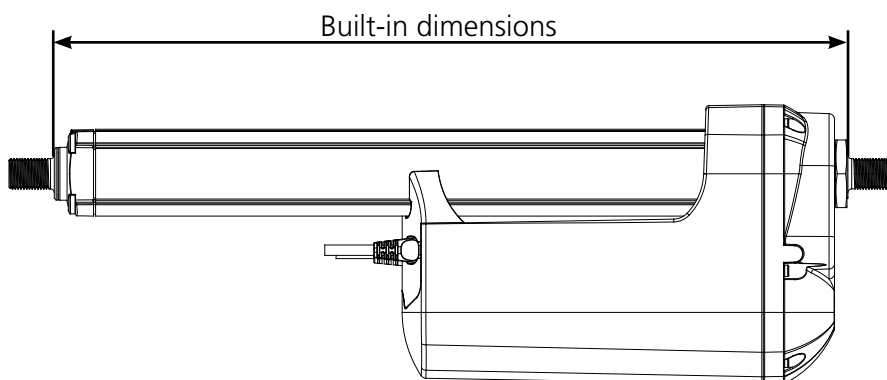
Built-in dimensions

All dimensions are in mm

The built-in dimension depends on the chosen safety option and stroke length(s).

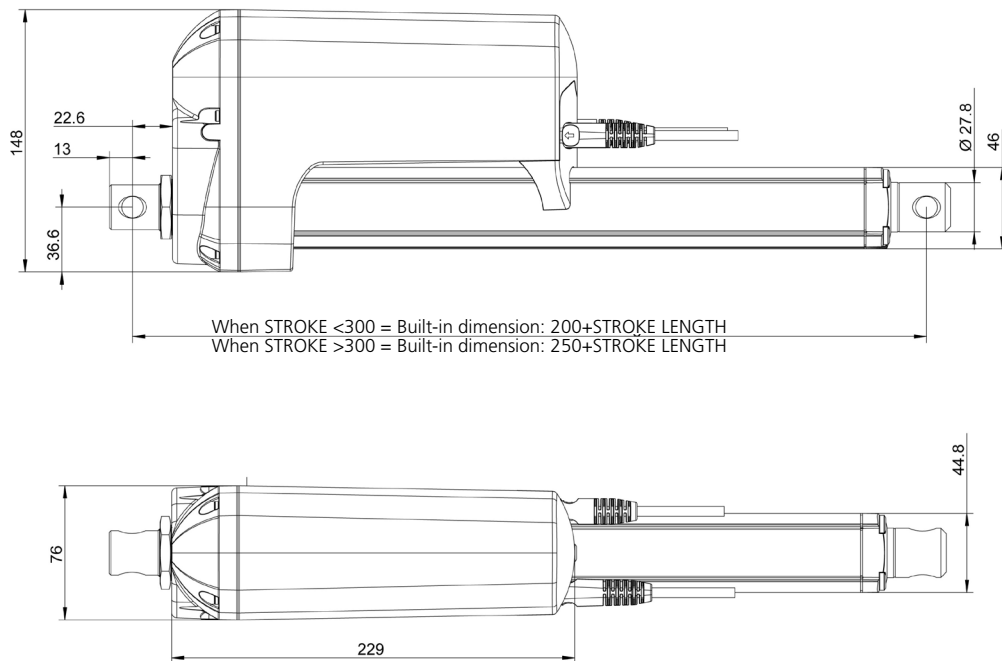
	Piston rod eye	Ball eye Ø20 H7 / to the centre of the hole	Ball eye Ø19.2 / to the centre of the hole	Solid Ø16.2 mm / to the centre of the hole	Solid Ø19.2 mm / to the centre of the hole	Male adapter M16 X 1.5 / from the surface*	Male adapter M20 X 1.5/ from the surface*
Back fixture		Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600
Solid Ø16.2 mm (0° and 90°) / to the centre of the hole		316 + stroke	316 + stroke	300 + stroke	300 + stroke	287 + stroke	287 + stroke
Solid Ø19.2 mm (0° and 90°) / to the centre of the hole		316 + stroke	316 + stroke	300 + stroke	300 + stroke	287 + stroke	287 + stroke
Male adapter M20 / from the surface*		297 + stroke	297 + stroke	281 + stroke	281 + stroke	267 + stroke*	267 + stroke*

* These built-in dimensions are measured according to the illustration below.



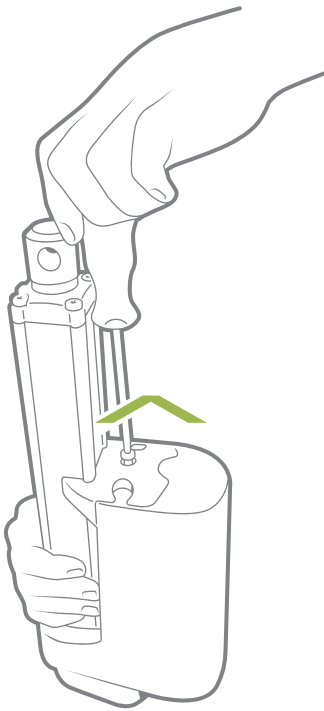
Built-in dimensions For Shot BID option

All dimensions are in mm.

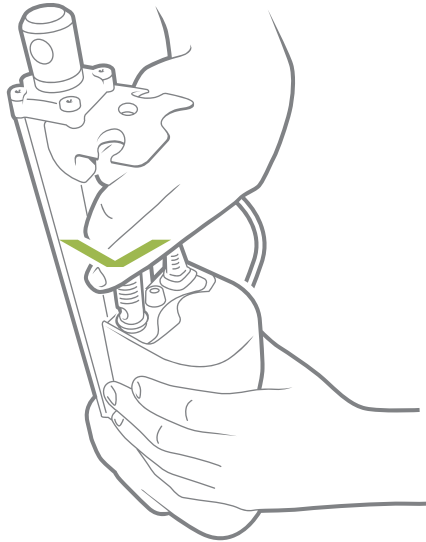


		Solid Ø12.2 mm (0° and 90°)		Solid Ø12.9 mm (0° and 90°)	
Stroke length		≤300	>300	≤300	>300
Back fixture		Solid to the centre of the hole		Solid to the centre of the hole	
Solid Ø12.2 mm	Solid to the centre of the hole	200 + stroke	250 + stroke	200 + stroke	250 + stroke
Solid Ø12.9 mm	Solid to the centre of the hole	200 + stroke	250 + stroke	200 + stroke	250 + stroke

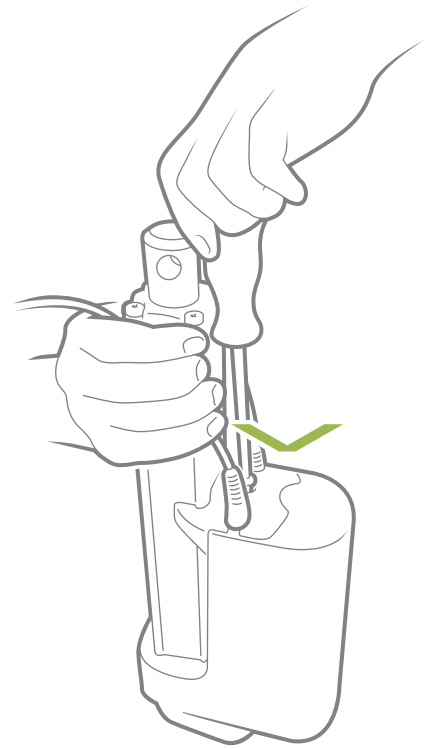
Cable mounting



1. Unscrew the cover and remove the two blind plugs.



2. Plug in the power cable and/or the signal cable.



3. Slide the cover onto the actuator.

The torque of the cover screw is approx. 3.5 ± 0.3 Nm

TORX 25IP



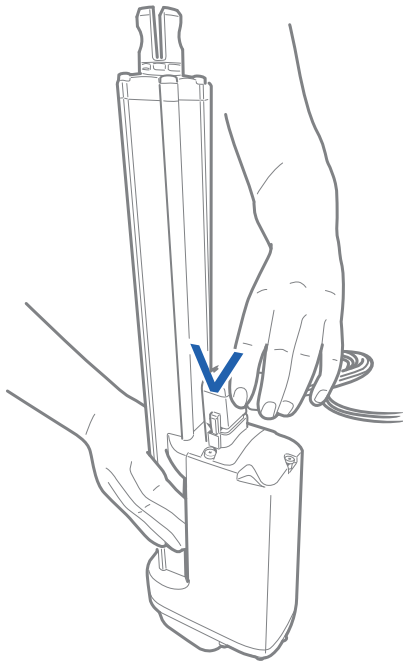
When changing the cables on a LINAK® actuator, it is important that this is done carefully, in order to protect the plugs and pins. Before the new cable is mounted, we recommend that the socket is greased with Vaseline®, to keep the high IP protection and ensure an easy mounting. Please be sure that the plug is in the right location and fully pressed in before the cable lid is mounted.

Remove the tinned cable end when the cable end is mechanically connected. The tinned end is only to be used when a soldered connection is made.

Please note that if the cables are mounted and dismantled more than 3 times, the plugs can be damaged. Therefore, we recommend that such cables are discarded and replaced. Also note that the cables should not be used for carrying the actuator.

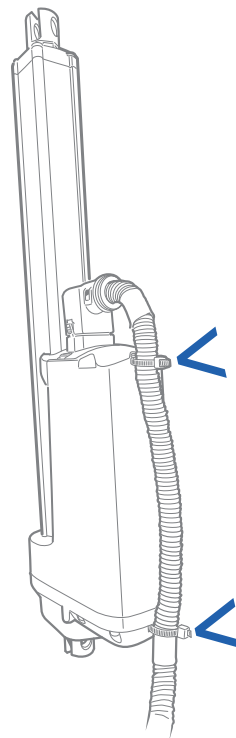
We recommend taking some precaution and designing the wire connection in such a way that the cable end is kept inside a closed, protected area to guarantee the high IP protection.

Mounting of cable Off-highway



1) Plug in the cable.

An audible "Click" confirms a correct mounting



2) Secure the cable with cable-ties to the two anchors



We recommend to take some precaution and design the wire connection in a way, where the cable end is kept inside a closed, protected area to guarantee the high IP protection.

Off-highway connection to Actuator Connect™

When connecting the actuator to Actuator Connect™ it is imperative to follow these instructions.

Power supply connection:

The actuator has to be powered with 12 Volt DC

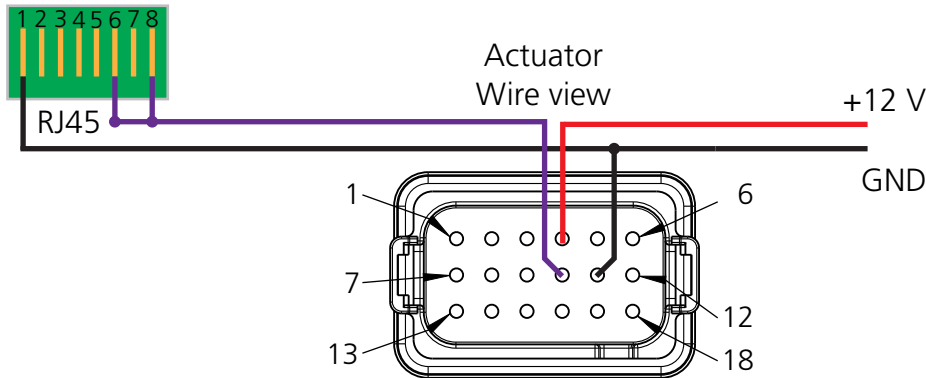
Positive is connected to pin 4 at the actuator

GND is connected to pin 11 at the actuator


RJ45:


Pin 1 at the RJ45 plug is Ground and has to be interconnected to GND on pin 11 at the actuator

Pin 6 and 8 at the RJ45 plug is communication and both has to be connected to pin 10 at the actuator:



Electrical installation

-  To ensure maximum self-locking ability, please make sure that the motor is shorted when stopped. Actuators with integrated controller provide this feature, as long as the actuator is powered.
- When using soft stop on a DC-motor, a short peak of higher voltage will be sent back towards the power supply. It is important when selecting the power supply that it does not turn off the output, when this backwards load dump occurs.
- When using actuators without integrated controller, it is strongly recommended to use a fuse between power supply and actuator.

 The power supply for actuators without integrated controller must be monitored externally and cut off in case of current overload.

Recommended fuse for power supplies and actuators without integrated controller:

Platform		Spindle pitch (mm)	Load max. (N)	Typical amp. at full load (A)			Recommended fuse		
				48 V	24 V	12 V	48 V	24 V	12 V
01	Standard with power switch	2.5	15,000	5.0	10.0	20.0	10.0	20.0	40.0
		8.0	10,000	4.0	8.0	-	8.0	16.0	-

Manual hand crank

The manual hand crank can be used in the case of a power failure and is only intended for emergency use.



The cover over the Allen key socket must be unscrewed before the Allen key can be inserted and the hand crank operated.

Hand crank torque: 6-8 Nm

Hand crank RPM: Max. 65

Piston rod movement per turn: Gear H = 4.0 mm



- The power supply has to be disconnected during manual operation.
- If the actuator is operated as a hand crank, it must only be operated by hand - otherwise there is a potential risk of overloading and thereby damaging the actuator. Do NOT use power tools to operate the hand crank!
- After using the hand crank, the ingress protection IP66 cannot be maintained.
- After using the hand crank, always return the actuator to the most inward position. Failing to do so can damage the actuator or the application it is used for.
- Actuators with absolute positioning must be initialised after use of the manual hand crank, because their positioning will be displaced when the power is disconnected.

Label for LA37



Designed in Denmark

DK - 6430 Nordborg

Type : 3702520000F346=614H30350ACS000

Item No. : 37XXXX-XX

Prod. Date : 2024.05.14

Max Load : Push 15000 N / Pull 15000 N IP66

Power Rate: 48 V^{DC}, Max. 8 A

Duty Cycle : 10%, Max 2 min. / 18 min.

Model : LA37IO ; FCC ID: XBE-LAXXIO ; IC: 12338B-LAXXIO



W/O# -0001

Made in Denmark



1. Type: 3702520000F346-614H30350ACS000

Describes the basic functionality of the product

2. Item no.: 37XXXX-XX

Sales and ordering code

3. Prod. Date: YYYY.MM.DD

Production date describes when the product has been produced. This date is the reference for warranty claims

4. Max. Load: Push 15000 N / Pull 15000 N IP66

Describes the maximum load that the product can be exposed to in compression and tension. This line also contains a reference to the product's IP protection degree

5. Power Rate: 48 V DC / Max. 8 Amp.

Input voltage for the product and maximum current consumption

6. Duty Cycle: 10%, Max. 2 min. / 18 min.

The duty cycle defines the maximum period during operation without interruption. After operation a pause must be observed. It is important that the operator follows the instructions of the duty cycle; otherwise, a possible overload may result in reduced product life/errors

7. W/O #-0001

The LINAK work order followed by a unique sequential identification number



DECLARATION OF CONFORMITY

LINAK A/S
 Smedevænget 8
 DK - 6430 Nordborg

hereby declares that

Actuator
 (LA361C) 36*****7*****; 36*****8*****; 36*****9*****; 36*****B*****
 (LA361C) 36*****03**_*****; (LA361C) 36*****13**_*****
 (LA361C) 36*****23**_*****; (LA361C) 36*****33**_*****
 (LA361C) 36*****43**_*****; (LA361C) 36*****53**_*****
 (LA361C) 36*****63**_*****

(LA371C) 37*****7*****; 37*****8*****; 37*****9*****; 37*****B*****
 (LA371C) 37*****03**_*****; (LA371C) 37*****13**_*****
 (LA371C) 37*****23**_*****; (LA371C) 37*****33**_*****
 (LA371C) 37*****43**_*****; (LA371C) 37*****53**_*****
 (LA371C) 37*****63**_*****

(The "*" in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the EMC Directive: 2014/30/EU according to following standards:
 EN 61000-6-1:2019, EN 61000-6-2:2019, EN 61000-6-3:2021, EN 61000-6-4:2019

complies with the ATEX Directive 2014/34/EU according to following standards:
 EN IEC 60079-0:2018, EN 60079-31:2014
 TÜV NORD CERT GmbH, Notified Body No. 0044. Certificate Number TÜV 15 ATEX 143747 X

complies with RoHS2 Directive 2011/65/EU according to the standard:
 EN 63000:2018

Nordborg, 2024-06-24

LINAK A/S
 John Kling, B.Sc.E.E.
 Regulatory Affairs Manager
 Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer

Original Declaration



DECLARATION OF CONFORMITY

LINAK A/S
Smedevænget 8
DK - 6430 Nordborg

hereby declares that

Actuator 36*****B32*-, 36*****B34*-, 36*****F32*-,
36*****F34*-, 36*****C32*-, 36*****C34*-,

37*****B32*-, 37*****B34*-, 37*****F32*-,
37*****F34*-, 37*****C32*-, 37*****C34*-

(The "*" in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the Radio Equipment Directive (RED) 2014/53/EU according to following standards:
EN 300 328 V2.2.2. (2019-07)
EN 301 489-1 V2.2.3 (2019-11), EN 301 489-17 V3.2.4 (2020-09)
EN IEC 62368-1:2020
EN 62479:2010
EN 50663:2017

complies with the ATEX Directive 2014/34/EU according to following standards:
EN IEC 60079-0:2018, EN 60079-31:2014
TÜV NORD CERT GmbH, Notified Body No. 0044. Certificate Number TÜV 15 ATEX 143747 X

complies with the RoHS2 Directive 2011/65/EU according to the standard:
EN 63000:2018

Additional information:

The system does comply with the selected parts of the standards:
EN IEC 61000-6-2:2019, Electromagnetic compatibility (EMC) – Part 6-2: Generic standards – Immunity for industrial environments
EN IEC 61000-6-4:2019: Electromagnetic compatibility (EMC) – Part 6-4: Generic standards – Emission standard for industrial environments

Nordborg, 2024-06-24

LINAK A/S
John Kling, B.Sc.E.E.
Regulatory Affairs Manager
Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer.
Original Declaration



DECLARATION OF CONFORMITY

LINAK A/S
Smedevænget 8
DK - 6430 Nordborg

hereby declares that

Actuator
(LA36 BUS) 36*****AD***B**
(LA36 BUS) 36*****04*****

(LA37 BUS) 37*****AD***B**
(LA37 BUS) 37*****04*****

(The '*' in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the EMC Directive: 2014/30/EU according to following standards:
EN 61000-6-1:2019, EN 61000-6-2:2019, EN 61000-6-3:2021, EN 61000-6-4:2019

complies with the ATEX Directive 2014/34/EU according to following standards:
EN IEC 60079-0:2018, EN 60079-31:2014
TÜV NORD CERT GmbH, Notified Body No. 0044. Certificate Number TÜV 15 ATEX 143747 X

complies with RoHS2 Directive 2011/65/EU according to the standard:
EN 63000:2018

Nordborg, 2024-06-24

LINAK A/S
John Kling, B.Sc.E.E.
Regulatory Affairs Manager
Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer

Original Declaration



DECLARATION OF CONFORMITY

LINAK A/S
Smedevænget 8
DK - 6430 Nordborg

hereby declares that

Actuator 36*****A72B=***** , 36*****A74B=***** , 36*****A82B=***** ,
36*****A84B=*****

37*****A72B=***** , 37*****A74B=***** , 37*****A82B=***** ,
37*****A84B=*****

(The "*" in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the EMC Directive 2014/30/EU according to following standards:
EN 61000-6-1:2019, EN 61000-6-2:2019, EN 61000-6-3:2021, EN 61000-6-4:2019

complies with the ATEX Directive 2014/34/EU according to following standards:
EN IEC 60079-0:2018, EN 60079-31:2014
TÜV NORD CERT GmbH, Notified Body No. 0044. Certificate Number TÜV 15 ATEX 143747 X

complies with the RoHS2 Directive 2011/65/EU according to the standard:
EN 63000:2018

Nordborg, 2024-06-24

LINAK A/S
John Kling, B.Sc.E.E.
Regulatory Affairs Manager
Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer.

Original Declaration



DECLARATION OF CONFORMITY

LINAK A/S
 Smedevænget 8
 DK - 6430 Nordborg

hereby declares that

Actuator 36*****142*-***** , 36*****144*-***** , 36*****0B2*-***** ,
 36*****0B4*-***** , 36*****E2*-***** , 36*****E4*-***** ,
 36*****A72*-***** , 36*****A74*-***** , 36*****A82*-***** ,
 36*****A84*-*****

76*****142*-***** , 76*****144*-***** , 76*****0B2*-***** ,
 76*****0B4*-***** , 76*****E2*-***** , 76*****E4*-***** ,
 76*****A72*-***** , 76*****A74*-***** , 76*****A82*-***** ,
 76*****A84*-*****

37*****142*-***** , 37*****144*-***** , 37*****0B2*-***** ,
 37*****0B4*-***** , 37*****E2*-***** , 37*****E4*-***** ,
 37*****A72*-***** , 37*****A74*-***** , 37*****A82*-***** ,
 37*****A84*-*****

77*****142*-***** , 77*****144*-***** , 77*****0B2*-***** ,
 77*****0B4*-***** , 77*****E2*-***** , 77*****E4*-***** ,
 77*****A72*-***** , 77*****A74*-***** , 77*****A82*-***** ,
 77*****A84*-*****

(The "*" in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the EMC Directive 2014/30/EU according to following standards:
 EN 61000-6-2:2019, EN 61000-6-4:2019

complies with the ATEX Directive 2014/34/EU according to following standards:
 EN IEC 60079-0:2018, EN 60079-31:2014
 TÜV NORD CERT GmbH, Notified Body No. 0044. Certificate Number TÜV 15 ATEX 143747 X

complies with the RoHS2 Directive 2011/65/EU according to the standard:
 EN 63000:2018

Nordborg, 2024-08-29

LINAK A/S
 John Kling, B.Sc.E.E.
 Regulatory Affairs Manager
 Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer.

Original Declaration



DECLARATION OF CONFORMITY

LINAK A/S
Smedevænget 8

DK - 6430 Nordborg

hereby declares that

Actuator
(LA36 Mobile) 36*****C6*****, 36*****D6*****,
36*****E6*****

(LA37 Mobile) 37*****C6*****, 37*****D6*****,
37*****E6*****

(The '*' in the product description can either be a character or a number, thereby defining the variation of the product)

complies with the EMC Directive: 2014/30/EU according to following standards:
EN 61000-6-1:2019, EN 61000-6-2:2019, EN 61000-6-3:2021, EN 61000-6-4:2019

complies with RoHS2 Directive 2011/65/EU according to the standard:
EN 63000:2018

Nordborg, 2024-02-16

LINAK A/S
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Authorized to compile the relevant technical documentation

This declaration of conformity is issued under the sole responsibility of the manufacturer.
Original Declaration

DECLARATION OF INCORPORATION OF PARTLY COMPLETED MACHINERY

LINAK A/S
Smedevænget 8
DK - 6430 Nordborg

LINAK A/S hereby declares that LINAK DESKLINE® products, characterised by the following models and types:

Control Boxes	CBD6S
Linear Actuators	DB5, DB6, DB14, LA23, LA31
Lifting Columns	DL1A, DL2, DL4S, DL5, DL6, DL8, DL9, DL10, DL11, DL12, DL14, DL15, DL16, DL17, DL18, DL19, DL20, DL21, BASE1, LC1
Desk Panels	DPA, DPB, DPH, DPF, DPG, DPT, DP, DP1CS, DPI
Wireless Controls	BP10
Accessories	BA001, BLE2LIN, CHUSB, DESK Sensor, DF2, Kick & Click, SLS, SMPS, USB2LIN, WiFi2LIN, DC Connector, RFRL

LINAK A/S hereby declares that LINAK HOMELINE® products, characterised by the following models and types:

Control Boxes	CBD6DC
Linear Actuators	LA10, LA18, LA40 HOMELINE
Dual Actuators	TD4, TD5
Controls	BP10, HC10, HC20, HC40
Accessories	BA002, CP, BLE2DC, BLE2LIN, LED Light Rail, MD1, SMPS, WiFi2LIN

LINAK A/S hereby declares that LINAK MEDLINE® & CARELINE® products, characterised by the following models and types:

Control Boxes	CA10, CA20, CA30, CA40, CA63, CAL40, CB6, CB6S, CB6P2, CB8, CB9, CBJ2, CBJ Care, CBJ Home, CO41, CO53, CO61, CO65, CO71, COL50, OPS, PJ2, PJB4
Linear Actuators	LA20, LA23, LA24, LA27, LA28, LA29, LA30, LA31, LA34, LA40, LA44
Lifting Columns	BL1, LC1, LC3
Controls	ABL, ACC, ACK, ACO, ACOM, ACL, DP, DPH, FS, FS3, FPP, HB30, HB70, HB80, HB100, HB190, HB200, HB400, HD80, HL70, HL400
Accessories	BA16, BA18, BA19, BA22, BAJ, BAJL, BAL40, BAL50, CH01, CHJ2, CHL40, CHL50, DJB, LIN2OB, MJB2, MJB5 Plus, Massage Motor, PJB4, QLCI2, SLS, SMPS10, UBL, UBL2, UBL4 Motion, USB-A Power Adapter

LINAK A/S hereby declares that LINAK TECHLINE® products, characterised by the following models and types:

Linear Actuators	LA12, LA14, LA23, LA25, LA30, LA33, LA35, LA36, LA37, LA76, LA77
Lifting Columns	LC3 IC
Accessories	FMB

comply with the following parts of the Machinery Directive 2006/42/EC, ANNEX I, Essential health and safety requirements relating to the design and construction of machinery: 1.5.1 Electricity supply

The relevant technical documentation is compiled in accordance with part B of Annex VII and this documentation or part hereof will be transmitted by post or electronically to a reasoned request by the national authorities.

This partly completed machinery must not be put into service until the final machinery into which it is to be incorporated has been declared in conformity with the provisions of the Machinery Directive 2006/42/EC where appropriate.

Nordborg, 2024-07-10



LINAK A/S

John Kling, B.Sc.E.E., Certification and Regulatory Affairs
Authorised to compile the relevant technical documentation

Original declaration



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