

Linear Actuator LA37 **Data Sheet**





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Preface

Dear User,

We are delighted that you have chosen a LINAK® product.

LINAK systems are high-tech products based on many years of experience in the manufacture and development of actuators, lifting columns, desk frames, electric control boxes, controls, batteries, accessories and chargers.

This User Manual does not address the end user. It is intended as a source of information for the equipment or system manufacturer only, and it will tell you how to install, use and maintain your LINAK electronics. The manufacturer of the end product has the responsibility to provide a User Manual, where relevant safety information from this manual is passed on to the end user.

We are convinced that your LINAK product/system will give you many years of problem-free operation.

Before our products leave the factory, they undergo both function and quality testing. Should you, nevertheless, experience problems with your product/system, you are always welcome to contact your supplier.

LINAK subsidiaries and some distributors situated all over the world have authorised service centres, which are always ready to help you. Locate your local contact information on the back page.

LINAK provides a warranty on all products. (See warranty section).

This warranty, however, is subject to correct use in accordance with the specifications, maintenance being done correctly, and any repairs being carried out at a service centre, which is authorised to repair LINAK products.

Changes in installation and use of LINAK systems can affect their operation and durability. The products may only be opened by authorised personnel.

This User Manual has been written based on the present technical knowledge. LINAK reserves the right to carry out technical modifications and keeps the associated information updated.

LINAK A/S



Terms of use

LINAK® takes great care in providing accurate and up-to-date information on its products. However, the user is responsible for determining the suitability of LINAK products for a specific application.

Due to continual development, LINAK products are subject to frequent modifications and changes. LINAK reserves the rights to conduct modifications, updates, and changes without any prior notice. For the same reason, LINAK cannot guarantee the correctness and actual status of imprinted information on its products.

LINAK uses its best efforts to fulfil orders. However, for the reasons mentioned above, LINAK cannot guarantee availability of any particular product at any given time. LINAK reserves the right to discontinue the sale of any product displayed on its website or listed in its catalogues or in other written material created and produced by LINAK, LINAK subsidiaries, or LINAK affiliates.

All sales are subject to the 'Standard Terms of Sale and Delivery for LINAK A/S' available on LINAK websites. LINAK and the LINAK logotype are registered trademarks of LINAK A/S. All rights reserved.



Introduction

Powerful electric linear actuator designed to handle high loads and demanding environments. It delivers long-lasting reliability as well as a wide choice of industrial control interfaces.

Safety instructions

Please read this safety information carefully.

Be aware of the following three symbols throughout the document:



Warning!

Failing to follow these instructions can cause accidents resulting in serious personal injury.



Recommendations

Failing to follow these instructions can result in the actuator suffering damage or being ruined.



Additional information

Usage tips or additional information that is important in connection with the use of the actuator.

Furthermore, ensure that all staff who are to connect, mount, or use the actuator are in possession of the necessary information and that they have access to this document.

Persons who do not have the necessary experience or knowledge of the product/products must not use the product/products. Besides, persons with reduced physical or mental abilities must not use the product/products, unless they are under surveillance or they have been thoroughly instructed in the use of the apparatus by a person who is responsible for the safety of these persons.

Moreover, children must be under surveillance to ensure that they do not play with the product.

Before you start mounting/dismounting, ensure that the following points are observed:

- The actuator is not in operation.
- The actuator is free from loads that could be released during this work.

Before you put the actuator into operation, check the following:

- The actuator is correctly mounted as indicated in the relevant user instructions.
- The equipment can be freely moved over the actuator's whole working area.
- The actuator is connected to a mains electricity supply/transformer with the correct voltage which is dimensioned and adapted to the actuator in question.
- Ensure that the voltage applied matches to the voltage specified on the actuator label.
- Ensure that the connection bolts can withstand the wear.
- Ensure that the connection bolts are secured safely.



During operation, please be aware of the following:

- Listen for unusual sounds and watch out for uneven running. Stop the actuator immediately if anything unusual is observed.
- Do not sideload the actuator.
- Only use the actuator within the specified working limits.
- Do not step on or kick the actuator.

When the equipment is not in use:

- Switch off the mains supply in order to prevent unintentional operation.
- Check regularly for extraordinary wear.

Classification

The equipment is not suitable for use in the presence of a flammable anaesthetic mixture with air or with oxygen or nitrous oxide.



Warnings

- Do not sideload the actuator.
- When mounting the actuator in the application ensure that the bolts can withstand the wear and that they are secured safely.
- If irregularities are observed, the actuator must be replaced.
- The standard actuator (without Integrated Controller) without clutch, is not allowed to run into a mechanical block -before reaching the end of stroke.



Recommendations

- Do not place load on the actuator housing.
- Prevent impact or blows, or any other form of stress to the housing.
- Ensure that the cable cover is mounted correctly. Use 3.5 Nm torque.
- Ensure that the duty cycle and the usage temperatures for LA37 actuators are respected.
- Ensure that the cable cannot be squeezed, pulled or subjected to any other stress.
- Furthermore, it will be good practice to ensure that the actuator is fully retracted in the "normal" position. The reason is that there will be a vacuum inside the actuator if it is extended which over time can lead to water entering the actuator.



Features

- 12 / 24 / 48 V DC Brushed motor permanent magnetic motor
- Load from 10,000 N 15,000 N
- Max. speed 10 mm/sec. depending on load and spindle pitch
- Stroke length from 100 mm to 600 mm (601 -1,000 mm as special item)
- Built-in endstops reached function
- Highly efficient acme thread spindle
- Heavy duty aluminium housing for harsh conditions
- Protection class: IP66 for outdoor use (dynamic). Furthermore, the actuator can be washed down by a high pressure cleaner (IP69K static)
- Highly efficient acme thread spindle
- Static holding load up to 45 kN in push and pull
- Dynamic wind stress loads 15 kN push/pull 100,000 times
- Hand crank for manual operation
- Integrated brake, high self-lock ability
- Endplay See <u>Technical Specifications</u>
- Non-rotating piston rod eye
- Noise level: 76 dB (A). Measuring method: DS/EN ISO 8746 (actuator not loaded)
- Current monitoring
- Off-highway Features:
 - 12 or 24 V DC brushed permanent magnetic motor
 - Load up to 15,000 N (depending on the spindle pitch)
 - Max. speed 10 mm/sec.
 - Reinforced aluminium housing for harsh conditions
 - IPC-A-610 Class 3 (High-performance electronic products)
 - IP54 without cable mounted IP69K with cable mounted with shell or moulded cable

An Off-highway vehicle is intended for use on steep or uneven ground and includes those used for construction or agriculture. They are specifically designed for off-road use.

Quad bikes, dirt bikes, dune buggies and other types of all-terrain vehicles are also types of Off-highway vehicles, although their function is very different from motor vehicles designed for industrial and farming use.



Options in general

- Back fixture can be ordered in steps of 90 degrees
- Exchangeable cables in different lengths
- Hall effect sensor
- Analogue or digital feedback for precise positioning
- Different back fixtures and piston rod eyes
- Endstop reached signals
- Built-in Zero Point or endstop switch initialisation principle
- IC options including:
 - I/O
 - Ethernet/IP
 - Modbus TCP/IP
 - Modbus RTU
 - IO-Link
 - LIN bus
 - CAN SAE J1939
 - CANopen
 - Off-highway LIN bus (contact LINAK sales)
 - Off-highway CAN SAE J1939
 - Off-highway CANopen

(see specific interface user manuals at the <u>TECHLINE webpage</u> for Connection Diagrams and I/O Specifications)

PC configuration tool (Actuator Connect[™] and BusLink)



Usage

• Duty cycle for actuators with a 0-600 mm stroke length is 10%

• Duty cycle for actuators with a 601-1,000 mm stroke length (special item) is 5%

• Ambient operating temperature Full performance from +5 °C to +40 °C

-30 °C (reduced load 50%) to + 85 °C (reduced duty cycle 10%)

• Storage temperature -40 °C to +70 °C

Actuator is not activated/connected. -40 °C to +85 °C for 72 hours

-55 °C to +95 °C for 24 hours for Standard platform

-55 °C to +105 °C for 24 hours for Integrated Control platform

Acclimatization before usage

Relative humidity
 Full performance from 20% to 80% - non-condensing

(Actuator is neither activated nor connected)

• Cyclic state 93% to 98% - non-condensing +25 °C to +55 °C for 12 hours

• Steady state 93% to 95% - non-condensing +40 °C for 56 days

Atmospheric pressure
 Meters above sea level
 Max. 3,000 meters

• Off-highway:

- For applications operated at constantly low temperatures it is recommended to use a stronger version of the actuator to reduce the current consumption that in some combinations can be up to 3 times higher (at -40° Celsius)

- Testet according to: ISO14982-1 / Agricultural and forestry machinery - Electromagnetic compatibility - Part 1: General EMC requirements (clamped capacitor circuit)

- Compliant with: ROHS2: 2011/65/EU: Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment EMC Directive - 2014/30/EU



Ordering example

37 080 200 0 A 01 B 6 - 6 1 2 H 3 XXXX A C S 0 0 0

Actuator 37 = LA37 type

Spindle type 025 $= 2.5 \, \text{mm}$ 080 = 8 mm

Stroke = XXX Length in mm (100-995) 200 A00 1000 Length in mm length

Safety 0 = No safety nut

Feedback 0 = No Feedback 9 = Hall Potentiometer, 2-wire

> Α = Hall Potentiometer Κ Single Hall Н = Dual Hall Χ Special

Platform 6-pin 9-pin

Endstop switch principle Zero Point

See Current = Standard with power switch = I/O Basic 01 В3 limits and 04 = Modbus C3 = I/O Customised Current 06 = LIN bus F3 = I/O Full cut-offs for 0B 07 = CAN SAE J1939 = IO-Link availability of = CANopen = Modbus RTU 80 14 voltage

Zero Point

16 = LIN bus

= CAN SAE J1939 17

18 = CANopen Zero Point with split supply

Α7 = CAN SAE J1939

8A = CANopen

0E = Modbus TCP/IP

2E = Ethernet/IP

4E = Profinet

18-pin Off-highway

C6* = LIN bus **

D6* = CAN SAE J1939

E6* = CANopen XX = Special

Motor type 1 = 12 V DC

> 4 = 48 V DC

2 = 24 V DC

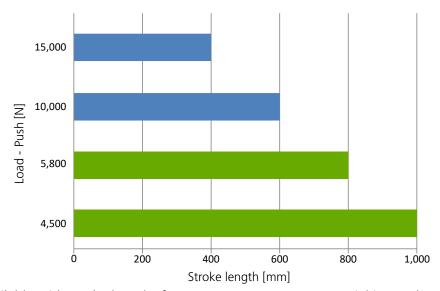
Requires Housing option 'C' IP66 Off-highway, also only available with Motor Type 1 or 2

^{**} Please contact LINAK for further information

						<u> </u>
Housing	6	=	IP66 - Reinforced house	C*	=	IP54 - Off-highway house
Not used	-	=	Not used			
Colour	6	=	Dark Olivish Grey NCS S7000-N			
Daak fisstessa	4		00	4		Mala Adaptor (outor throad)
Back fixture	1 2	=	0°	4 X	=	Male Adapter (outer thread) Special
Piston rod eye	2	=	Solid	6	=	Ball eye
СуС	4	=	Male Adapter (Outer thread)	X	=	Special
Gear	Н	=	Ratio 1:46			
Brake	3	_	Push/Pull			
D. G. C.	J		1 d 3. W 1 d 11			
Built-in dimension	xxxx	=	Measured in mm			
Endstop	Α	=	A_HIGH / A_HIGH	J	=	A_HIGH / LOW
reached	В		A_LOW / A_HIGH	K		A_LOW / LOW
output	C	=	A_HIGH / A_LOW	L	=	A_HIGH / HIGH
	D	=	A_LOW / A_LOW	М	=	A_LOW / HIGH
	Е	=	LOW / A_HIGH	N**	=	LOW / LOW
	F	=	HIGH / A_HIGH	Ο	=	HIGH / LOW
	G	=	LOW / A_LOW	Р	=	LOW / HIGH
	Н	=	HIGH / A_LOW	Q	=	HIGH / HIGH
				Χ	=	Special
Plug type	0***	=	No plug (when no cable is chosen)	Н	=	AMP
3 71	J	=	Deutsch	K	=	AMP Super Seal
	9	=	Deutsch - Moulded	7	=	AMP Super Seal - Moulded
	C	=	Flying leads	E****	=	M12 Y Ethernet/IP
	Ν	=	M12 IO-Link	R	=	M12 Modbus
				Χ	=	Special
Cable	0***	=	No cable selected	А	=	Mounted with 90° angled connectors
	S****	=	Straight cable	Υ	=	Y-Cable (combined power and signal cable)
				Χ	=	Special
* ** ** **	Manda Shall b Actuat	itor e cl ors	latform option 18-pin Off-highway - y for CAN SAE J1939, CANopen, LIN nosen with 'Off-highway' with Ethernet/IP are only compatibl number: CAB0367402)	l bus, M	odb	ous and IO-Link

Parallel mode	0	= The system is NOT parallel	2-8	= Critical parallel (number of actuators in the parallel system)
SW config.	0	= Standard software	X	= Special software
Not used	0			

Load vs stroke length



Jhm

LA37 is available with stroke lengths from 601 to 1,000 mm as special item. Please note:

- For applications that only operate in pull the limitations are 1,000 mm stroke with both 10,000 and 15,000 N load
- Safety factor 2

Technical specifications

12 V

Load max. (N)	Self-lock min. (N)	Pitch (mm/ spindle	Hall resolution (mm/count)	Endplay (mm)	Typical speed (mm/s)		Standard stroke lengths	Typical (A)	amp.
		rev.)			No load	Full load	(mm)	No load	Full load
15000	20000	2.5	0.034	2	3.5	2.2	100-400	4.0	22.5
10000	15000	2.5	0.034	2	3.5	2.8	400-600	4.0	15.0
10000	15000	8.0	0.110	2	11.0	9.0	100-600	4.0	23.0

24 V

Load max. (N)	Self-lock min. (N)	Pitch (mm/ spindle	Hall resolution (mm/	Endplay (mm)	Typical speed (mm/s)		Standard stroke lengths	Typical (A)	amp.
		rev.)	count)		No load	Full load	(mm)	No load	Full load
15000	20000	2.5	0.034	2	3.5	2.8	100-400	2.0	13.0
10000	20000	2.5	0.034	2	3.5	3.0	400-600	2.0	8.0
10000	15000	8.0	0.110	2	11.0	9.0	100-600	2.0	13.0

48 V

Load max. (N)	Self-lock min. (N)	Pitch (mm/ spindle	Hall resolution (mm/count)	Endplay (mm)	Typical speed (mm/s)		Standard stroke lengths	Typica (A)	l amp.
		rev.)	No load	Full load		No load	Full load		
15000	20000	2.5	0.034	2	3.5	2.5	100-400	1.0	6.0
10000	20000	2.5	0.034	2	3.5	3.2	400-600	1.0	4.0
10000	15000	8.0	0.110	2	11.0	9.0	100-600	1.0	6.0

See Current limits and Current cut-offs for availability of voltage

- To ensure maximum self-locking ability, please make sure that the motor is shorted when stopped Actuators with Integrated Controller provide this feature, as long as the actuator is powered.
- When using soft stop on a DC-motor, a short peak of higher voltage will be sent back towards the power supply. It is important when selecting the power supply that it does not turn off the output when this backwards load dump occurs.



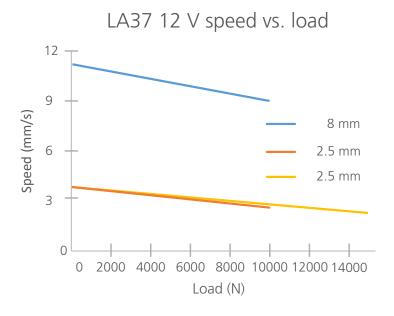
A Hall pulse consists of two Hall counts. A Hall count occurs every time the signal changes state (high to low or vice versa).

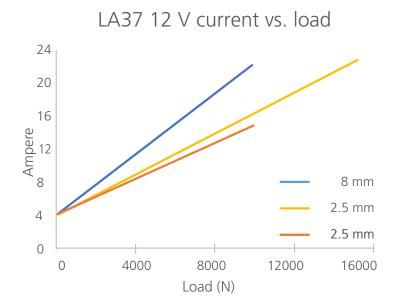


The typical values can have a variation of \pm 20% on the current values and \pm 10% on the speed values. Measurements are made with an actuator in connection with a stable power supply and an ambient temperature of 20°C.

Speed and current curves

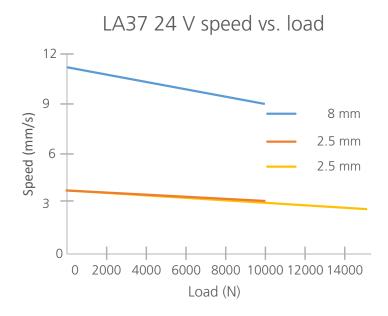
The typical values below are made with a nominal power supply of 12 V DC and an ambient temperature of 20° C.

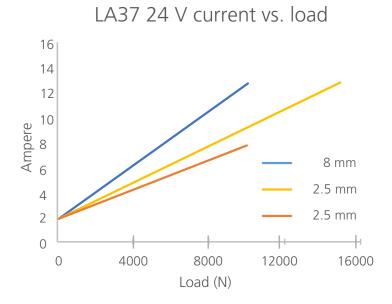




Speed and current curves

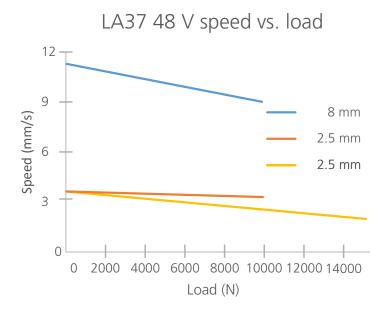
The typical values below are made with a nominal power supply of 24 V DC and an ambient temperature of 20°C.

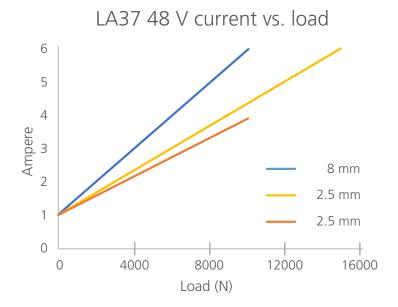




Speed and current curves

The typical values below are made with a nominal power supply of 48 V DC and an ambient temperature of 20°C.





Current limits

As described in the algorithm on previous page.

Platf	orm	12 V	24 V	48 V	Reference temperature: 0°C
B3 C3	I/O Basic I/O Customised	26 A	13 A	8 A	Above
F3	I/O Full	26 A	26 A	13 A	Below
۸۶	LIN bus	-	13 A	8 A	Above
A6		-	26 A	13 A	Below
OB	IO-Link	-	16 A	-	Above
OB	IO-LITIK	-	26 A	-	Below
14	Modbus RTU	-	16 A	8 A	Above
14	Modbus KTO	-	26 A	15 A	Below
C6 D6	LIN bus Off-highway CAN SAE J1939 Off-highway CANopen Off-highwayv	26 A	13 A	-	Above
E6		26 A	26 A	-	Below

Platfo	orm	12 V	24 V	48 V	Reference temperature: 0°C
A7	A7 CANbus J1939	-	13 A	8 A	Above
A8	CANopen	-	26 A	13 A	Below
0E 2E		-	16 A	8 A	Above
4E	Profinet	-	26 A	16 A	Below

Max. current

The current is not limited by the actuator. Below is the anticipated consumption at max. load. See: Recommended fuse for actuators without Integrated Controller.

Platfo	rm	12 V	24 V	48 V	Reference temperature: 0°C
0.4	Standard with power switch	26 A	13 A	8 A	Above
01		26 A	13 A	8 A	Below



Current cut-offs

The principle behind the current cut-off measurement is an 'above limit' and a 'below limit' accumulating counter. When the time-out counter reaches a specific value the current cut-off goes into effect. The timeout value is pre-set at 200 ms.

Platf	orm	12 V	24 V	48 V	Reference temperature: 0°C
0.4	04 Modbus	-	13 A	-	Above
04		-	13 A	-	Below
06	LIM bus	30 A	-	-	Above
06	LIN bus	30 A	-	-	Below
07	CAN SAE J1939 CANopen	30 A	20 A	-	Above
08		30 A	25 A	-	Below

Platform		12 V	24 V	48 V	Reference temperature: 0°C
16	LINI bus	30 A	-	-	Above
10	LIN bus	30 A	-	-	Below
17	CAN SAE J1939	30 A	20 A	13 A	Above
18 CANopen	CANopen	30 A	25 A	15 A	Below

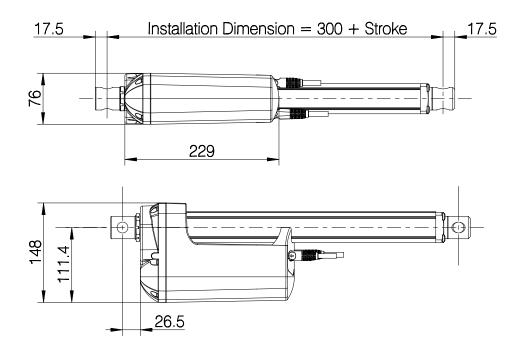


Stroke and built-in tolerances

Pla	tforms	Stroke tolerance	Example for 200 mm stroke	BID tolerance	Example for 400 mm BID
01	Standard with power switch	+0/-4 mm	196 to 200 mm	± 4 mm	396 to 404 mm
04 06 07 08	Modbus LIN bus CAN SAE J1939 CANopen	+0/-6 mm	194 to 200 mm	± 4 mm	396 to 404 mm
16 17 18	LIN bus CAN SAE J1939 CANopen	± 2 mm	198 to 202 mm	± 2 mm	398 to 402 mm
B3 C3 F3 A6 OB 14 A7 A8 4E 2E OE C6 D6 E6	I/O Basic I/O Customised I/O Full LIN bus IO-Link Modbus RTU CAN SAE J1939 CANopen Profinet Ethernet/IP Modbus TCP/IP LIN bus Off-highway CAN SAE J1939 Off-highway CANopen Off-highway	± 2 mm	198 to 202 mm	± 2 mm	398 to 402 mm

Built-in dimensions

All dimensions are in mm

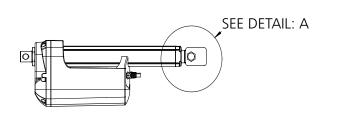


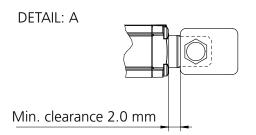
The above dimensions apply for all LA37 piston rod eyes and back fixtures.

Keep a clearance when mounting a bracket



When mounting a custom bracket on the moving part of the actuator, please observe the minimum clearance between bracket and cylinder top when fully retracted. This will prevent jamming and destruction of the actuator drive train.





With Zero Point the minimum stroke is 70 mm.

The Zero Point initialisation zone is located between 35-70 mm going from the most inward position.

The movement passing the zone has to be stable for the initialisation to succeed - also, no virtual limits can be set in the initialisation zone.

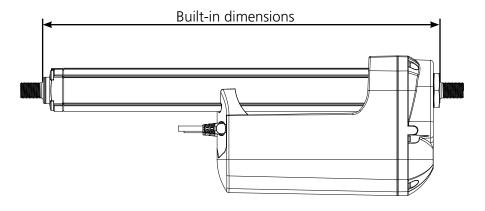
Built-in dimensions

All dimensions are in mm

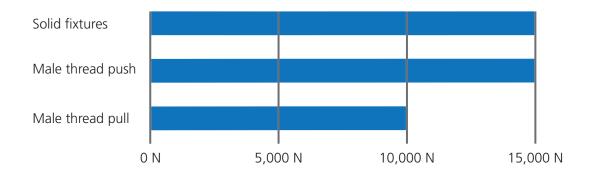
The built-in dimension depends on the chosen safety option and stroke length(s).

	Piston rod eye	Ball eye Ø20 H7 / to the centre of the hole	Ball eye Ø19.2 / to the centre of the hole	Solid Ø16.2 mm / to the centre of the hole	Solid Ø19.2 mm / to the centre of the hole	Male adapter M16 X 1.5 / from the surface*	Male adapter M20 X 1.5/ from the surface*
Back	fixture	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600	Stroke from 100 to 600
mm (90°) /	Ø16.2 0° and to the e of the	316 + stroke	316 + stroke	300 + stroke	300 + stroke	287 + stroke	287 + stroke
mm (90°) /	Ø19.2 0° and to the e of the	316 + stroke	316 + stroke	300 + stroke	300 + stroke	287 + stroke	287 + stroke
Male adapt / fron surfa		297 + stroke	297 + stroke	281 + stroke	281 + stroke	268 + stroke*	268 + stroke*

^{*} These built-in dimensions are measured according to the illustration below.



Durability for piston rod eyes and back fixtures



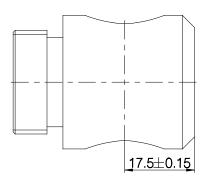
Blue = Full lifetime

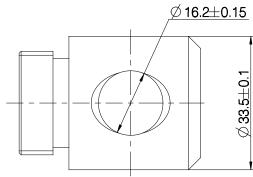
Piston rod eyes

Option "2"

LINAK P/N: 0361387

Free-cutting steel with galvanised surface

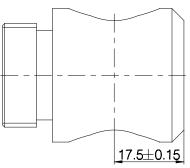


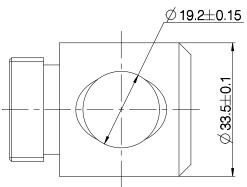


Option "2"

LINAK P/N: 0361393

Free-cutting steel with galvanised surface

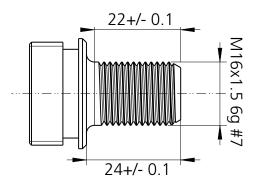


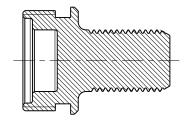


Option "4"

LINAK P/N: 0361135

AISI 303

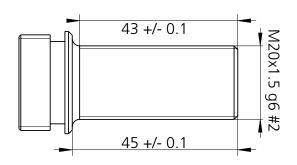


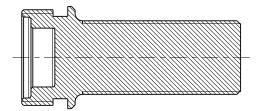


Option "4"

LINAK P/N: 0371044

AISI 303







The piston rod eye is only allowed to turn 0 - 180 degrees.

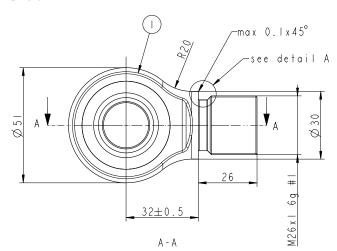
Piston rod eyes

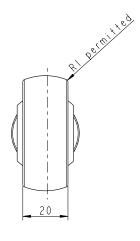
Option "6"

LINAK P/N: 0361568 (Ø20H7)

 $0361571\,(\emptyset 19.2\pm 0.1)$

AISI 304







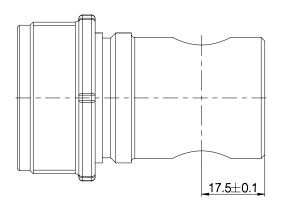
The piston rod eye is only allowed to turn 0 - 180 degrees.

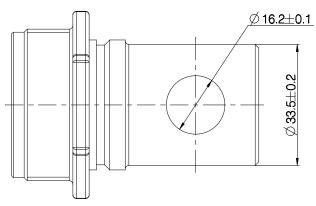
Back fixtures

Option "1&2"

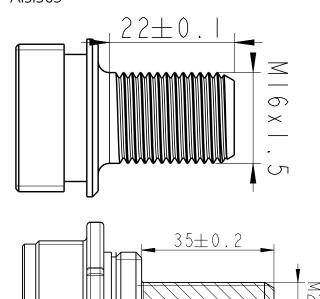
LINAK P/N: 0371019

Free-cutting steel with galvanised surface



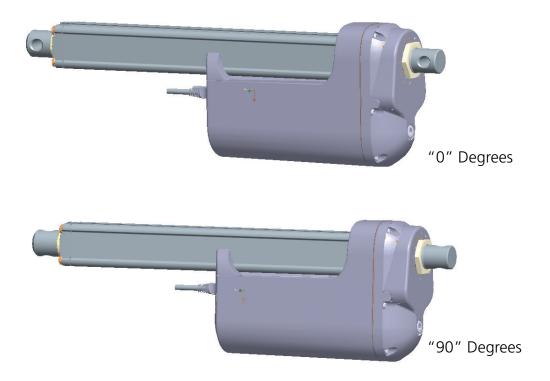


Option "4" - Max. 10,000 N in Pull . LINAK P/N: 0361135 (M16) & 0371247 (M20) AISI303





Back fixture orientation

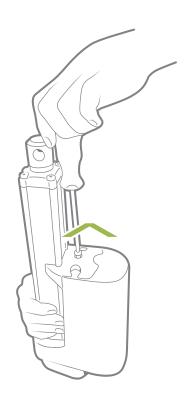


Off-highway housing

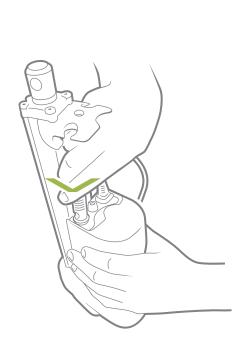
A reinforced vibration proof aluminium housing with a integrated 18-pin connector tested to even higher standards.

NB. All with tolerance of ±4°

Cable mounting



1. Unscrew the screw and separate the cover from the housing. Remove the blind plug(s).



2. Plug in the power cable and/or the signal cable.



3. Slide the cover onto the actuator.

The torque of the cover screw is approx. $3.5 \pm 0.3 \text{ Nm}$

TORX 25IP



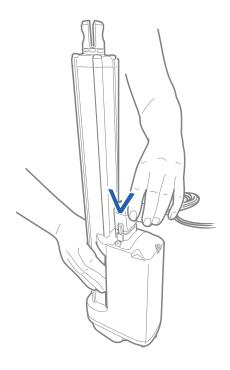
When changing the cables on a LINAK® actuator, it is important that this is done carefully, in order to protect the plugs and pins. Before the new cable is mounted, we recommend that the socket is greased with Vaseline®, to keep the high IP protection and ensure an easy mounting. Please be sure that the plug is in the right location and fully pressed in before the cable lid is mounted.

Remove the tinned cable end when the cable end is mechanically connected. The tinned end is only to be used when a soldered connection is made.

Please note that if the cables are mounted and dismounted more than 3 times, the plugs can be damaged. Therefore, we recommend that such cables are discarded and replaced. Also note that the cables should not be used for carrying the actuator.

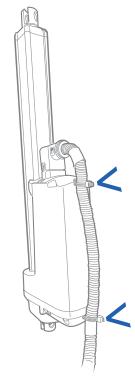
We recommend taking some precaution and designing the wire connection in such a way that the cable end is kept inside a closed, protected area to guarantee the high IP protection.

Mounting of cable Off-highway



1) Plug in the cable.

An audible "Click" confirms a correct mounting



2) Secure the cable with cable-ties to the two anchors

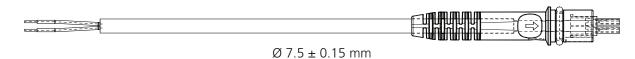


We recommend to take some precaution and design the wire connection in a way, where the cable end is kept inside a closed, protected area to guarantee the high IP protection.

Cables

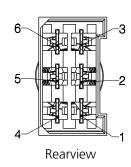
Power cable dimensions LINAK® P/N 0367046

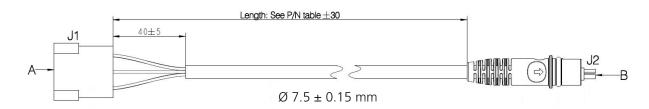
Colour	Outer dimensions	Core mm ²	AWG
Brown	Ø2.8 mm	2.0	14
Blue	Ø2.8 mm	2.0	14



6-pin Signal cable dimensions LINAK P/N 0367049

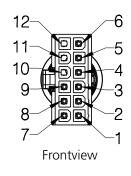
Colour	Outer dimensions	Core mm ²	AWG
Violet	Ø1.5 mm	0.5	20
Black	Ø1.5 mm	0.5	20
Red	Ø1.5 mm	0.5	20
Yellow	Ø1.5 mm	0.5	20
Green	Ø1.5 mm	0.5	20
White	Ø1.5 mm	0.5	20





9-pin Signal cable dimensions LINAK P/N 0368543

Colour	Outer dimensions	Core mm ²	AWG	Pin
Orange	Ø1.5 mm	0.5	20	5
Black	Ø1.5 mm	0.5	20	1
Red	Ø1.5 mm	0.5	20	2
Light Blue	Ø1.5 mm	0.5	20	6
Yellow	Ø1.5 mm	0.5	20	3
Green	Ø1.5 mm	0.5	20	4
Grey	Ø1.5 mm	0.5	20	0
Violet	Ø1.5 mm	0.5	20	7
White	Ø1.5 mm	0.5	20	8

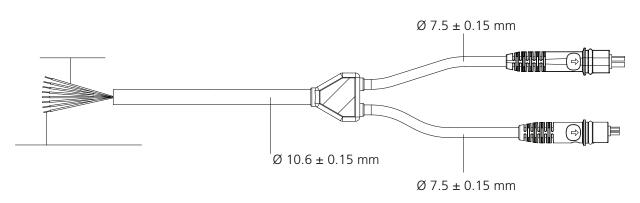


Cables

Y-cable dimensions LINAK® P/N 0367020

Colour	Outer dimensions	Core mm ²	AWG	Pin*
Brown	Ø2.8 mm	2.0	14	2
Blue	Ø2.8 mm	2.0	14	1
Red	Ø1.5 mm	0.5	20	4
Black	Ø1.5 mm	0.5	20	3
Yellow	Ø1.5 mm	0.5	20	7
Green	Ø1.5 mm	0.5	20	8
White	Ø1.5 mm	0.5	20	5
Violet	Ø1.5 mm	0.5	20	6

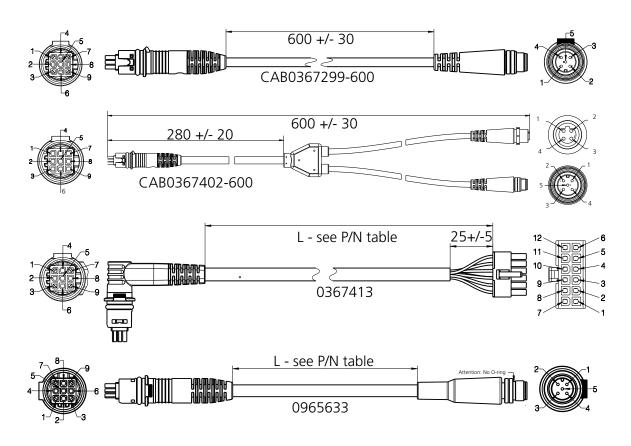
^{*} Pin connections are the same for both AMP and Deutsch connectors



	Cable P/N Table				
LINAK P/N	Cable type	# Wires	mm²	AWG	Length in mm
0367006	Power cable with AMP	2	2.0	14	200
CAB0367046-0400	Power cable	2	2.0	14	400
CAB0367046-0600	Power cable	2	2.0	14	600
CAB0367046-1500	Power cable	2	2.0	14	1,500
CAB0367046-5000	Power cable	2	2.0	14	5,000
CAB0367049-0600	Signal cable	6	0.5	20	600
CAB0367049-1500	Signal cable	6	0.5	20	1,500
CAB0367049-2000	Signal cable	6	0.5	20	2,000
CAB0367049-3000	Signal cable	6	0.5	20	3,000
CAB0367049-5000	Signal cable	6	0.5	20	5,000
CAB0368543-1500	Signal cable	9	0.5	20	1,500
CAB0368543-5000	Signal cable	9	0.5	20	5,000

^{*}AWG: American Wire Gauge

Cable P/N Table						
LINAK P/N	N Cable type		# Wires	mm²	AWG	Length in mm
CAB0367299-600	Signal cable fo	or IO-Link	9	0.5	20	600
CAB0367402-600	Signal Y-cable Ethernet/IP	Signal Y-cable for Ethernet/IP		0.5	20	600
0367413-XXXX	Signal cable w	Signal cable w. 90° plug		0.5	20	600 1,500 5,000
0965633-1000	Signal cable fo	Signal cable for Modbus		0.5	20	1000
CAB0367020-XXXX	Y-Cable	Signal	6	0.5	20	1 F00 F 000
CABU307020-XXXX	Y-Cable	Power	2	2.0	14	1,500 5,000
0367430-XXXX	Y-Cable	Signal	9	0.5	20	1,500 5,000
0307430-	1-Cable	Power	2	2.0	14	10,000
CAB0367440-XXXX	Y-Cable w.	Signal	9	0.5	20	1,500 5,000
	90° plug	Power	2	2.0	14	10,000



Cable kit article numbers

	BusLink cable kits				
Platform		Article no. Connection		Includes	Colour
04	Modbus (IC)	1. 0964561-A 2. USB2LIN06-C	RJ45	Adapter USB2LIN cable	Yellow
07 08	CAN SAE J1939 CANopen	0367997	RJ45	(Adapter + USB2Lin)	Green

Cable kit article numbers

	Actuator Connect™ cable kits				
Plat	form	Article no.	Pins	Includes	Colour
B3 C3 F3 A7 A8 OB 14 A7 A8 4E 2E OE	I/O Basic I/O Customised I/O Full CAN SAE J1939 CANopen IO-Link Modbus RTU CAN SAE J1939 CANopen Profinet Ethernet/IP Modbus TCP/IP	0367996	Signal-power + RJ45	(Adapter + USB2Lin)	Grey



Latest versions of both BusLink and Actuator Connect can be downloaded at the **LINAK/TECHLINE** page.

Off-highway connection to Actuator Connect™

When connecting the actuator to Actuator Connect™ it is imperative to follow these instructions.

Power supply connection:

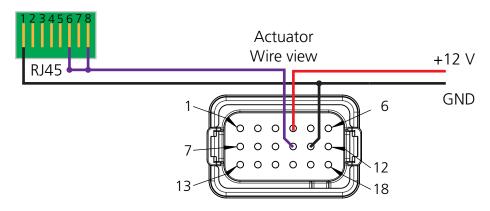
The actuator has to be powered with 12 Volt DC

Positive is connected to pin 4 at the actuator

GND is connected to pin 11 at the actuator

RJ45:

Pin 1 at the RJ45 plug is Ground and has to be interconnected to GND on pin 11 at the actuator Pin 6 and 8 at the RJ45 plug is communication and both has to be connected to pin 10 at the actuator:



Electrical installation



- To ensure maximum self-locking ability, please make sure that the motor is shorted when stopped. Actuators with integrated controller provide this feature, as long as the actuator is powered.
- When using soft stop on a DC-motor, a short peak of higher voltage will be sent back towards the power supply. It is important when selecting the power supply that it does not turn off the output, when this backwards load dump occurs.
- When using actuators without integrated controller, it is strongly recommended to use a fuse between power supply and actuator.



The power supply for actuators without integrated controller must be monitored externally and cut off in case of current overload.

Manual hand crank

The manual hand crank can be used in the case of a power failure and is only intended for emergency use.



6* mm Allen key

The cover over the Allen key socket must be unscrewed before the Allen key can be inserted and the hand crank operated.

Hand crank torque: 6-8 Nm Hand crank RPM: Max. 65

Piston rod movement per turn: Gear H = 4.0 mm

* 5 mm Allen key -if stainless steel piston rod eye and back fixture are chosen



- The power supply has to be disconnected during manual operation.
- If the actuator is operated as a hand crank, it must only be operated by hand - otherwise there is a potential risk of overloading and thereby damaging the actuator. Do NOT use power tools to operate the hand crank!
- After using the hand crank, the ingress protection IP66 cannot be maintained.
- After using the hand crank, always return the actuator to the most inward position. Failing to do so can damage the actuator or the application it is used for.
- Actuators with absolute positioning must be initialised after use of the manual hand crank, because their positioning will be displaced when the power is disconnected.

Environmental tests - Climatic

Test	Specification	Comment
Cold test	EN60068-2-1 (Ab)	Storage at low temperature: Temperature: -40°C Duration: 72 h Not connected Tested at room temperature.
	EN60068-2-1 (Ad)	Storage at low temperature: Temperature: -30°C Duration: 2 h Actuator is not activated/connected Tested at low temperature.
	EN60068-2-2 (Bb)	Storage at high temperature: Temperature: +90°C Duration: 72 h Actuator is not activated/connected Tested at room temperature.
Dry heat		Storage at high temperature: Temperature: +70°C Duration: 1000 h Actuator is not activated/connected Tested at high temperature.
	EN60068-2-2 (Bd)	Operating at high temperature: Temperature: +60°C Int. max. 17% Duration: 700 h Actuator is activated Tested at high temperature.
	EN60068-2-14 (Na)	Rapid change of temperature: High temperature: +100°C in 60 minutes Low temperature: -30°C in 60 minutes Transition time: <10 seconds Duration: 100 cycles Actuator is not activated/connected Tested at room temperature.
Change of temperature	EN60068-2-14 (Nb)	Controlled change of temperature: Temperature change 5°C pr. minute High temperature: +70°C in 60 minutes Low temperature: -30°C in 30 minutes 130 minutes per cycle Duration: 1,000 cycles (90 days) Actuator is not activated/connected Tested at 250, 500 and 1000 cycles at low and high temperatures.



Environmental tests - Climatic

Damp heat	EN60068-2-30 (Db)	Damp heat, cyclic: Relative humidity: 93-98% High temperature: +55°C in 12 hours Low temperature: +25°C in 12 hours Duration: 21 cycles * 24 hours Actuator is not activated/connected Tested within 1 hour after condensation, after upper temperature has been reached. Damp heat, steady state: Relative humidity: 93-95% Temperature: +40 ± 2°C Duration: 56 days Actuator is not activated/connected Tested within one hour after exposure.
Salt spray test		Actuators are tested for corrosion resistance at 500 hours salt spray test.
Degrees of protection IPX6 static		IPX6 static: Actuators are tested for water ingress according to IPX6, without movement. IPX4 dynamic: Actuators are tested in rainy conditions with movement. IP6X: Actuators are tested for dust sealing properties according to IP6X.
Chemicals	BS7691 / 96 hours	Diesel 100% Hydraulic oil 100% Ethylene Glucol 50% Urea Nitrogen saturated solution Liquid lime 10% (Super- Cal) NPK Fertilizer (NPK 16-4-12) saturated Tested for corrosion.
Climate test with Modbus PCB		Actuators with Modbus PCB are tested with 10.000 N load at temperatures of +5°C and +40°C.
Climate test with Hall PCB		Actuators with Hall PCB are tested with 15.000 N load at temperatures of -30°C and +70°C.



Environmental tests - Mechanical

Test	Specification	Comment
Free fall		Free fall from all sides: Height of fall: 0.4 meter onto steel. Actuator not activated/connected.
Vibration	EN60068-2-36 (Fdb)	Random vibration: Short time test: 6.29 g RMS Actuator is not connected Long time test: 7.21 g RMS Actuator is not connected Duration: 2 hours in each direction
	EN 60068-2-6 (Fc)	Sinus vibration: Frequency 5-25Hz: Amplitude = 3.3 mm pp Frequency 25-200Hz: Acceleration 4 g Number of directions: 3 (X-Z-Y) Duration: 2 hours in each direction Actuator is not activated.
Bump	EN60068-2-29 (Eb)	Bump test: Level: 40 g Duration: 6 milliseconds Number of bumps: 500 shocks in each of 6 directions. Actuator is not connected.
Shock	EN60068-2-27 (Ea)	Shock test: Level: 100g Duration: 6 milliseconds Number of bumps: 3 shocks in each of 6 directions. Actuator is not connected.
Static load		Static push and pull tests of basic actuators with 500, 750 and 1000mm strokes.
Dynamic load		Dynamic push/pull tests of the actuator.
Self-locking test		Self-locking tests at dynamic and static load.
Abuse test		Tests at 100% duty cycle until damage.
Lifetime test		Lifetime tests performed at combined loads in push and pull situations.



Environmental tests - Electrical

Test	Specification	Comment	
		Operating voltages +10 V - +16 V	
		Overvoltage +26 (V) / 5 min.	
Power supply	ASAE EP455 (1990)	Reverse polarity –26 (V) / 5 min.	
		Short circuit to ground 16 (V) / 5 min.	
		Short circuit to supply 16 (V) / 5 min.	
HF-immunity	EN61000-6-2	Level: 30 V/m. at 26 MHz – 1000 mHz	
		80% 1 KHz	
Emmision	EN61000-6-4	Level is inside limits for 12 V motor	
Insulation test		Level: 500 VAC/25-100 hz for 1 minute	
Automotive transients	ISO 7637	Load dump test only accepted on motor power connection.	
transients			
Current and speed		Actuators with loads of 0 N, 7.500 N and 15.000 N are tested at -30°C, +20°C and 70°C	



 γ All electrical and radiated emission (EMC) tests are conducted.

Environmental tests – Climatic - LA37 Off-highway

Test	Specification	Comment
Cold Test	EN60068-2-1 (Ab)	Storage at low temperature: Temperature: -55 °C Duration: 72 h Actuator is not activated/connected Tested at room temperature.
	EN60068-2-1 (Ad)	Operating at low temperature: Temperature: -40 °C Duration: 16 h Actuator is not activated/connected. Tested at low temperature.
Dry Heat	EN60068-2-2 (Bb)	Storage at high temperature: Temperature: +105 °C Duration: 72 h Actuator is not activated/connected. Tested at room temperature
		Storage at high temperature: Temperature: +70 °C Duration: 1000 h Actuator is not activated/connected Tested at high temperature.
	EN60068-2-2 (Bd)	Operating at high temperature: Temperature: +60 °C Int. max. 17 % Duration:700 h Actuator is activated Tested at high temperature.
Change of Temperature	EN60068-2-14 (Na)	Rapid change of temperature: High temperature: +105 °C in 60 minutes. Low temperature: -40 °C in 60 minutes. Transition time: <10 seconds Duration: 117 cycles Actuator is not activated/connected. Tested at room temperature.
	EN60068-2-14 (Nb)	Controlled change of temperature: Temperature change 5 °C pr. minute High temperature: +70 °C in 60 minutes. Low temperature: -30 °C in 30 minutes. 130 minutes pr. Cycle. Duration: 1.000 cycles (90 days) Actuator is not activated/connected. Tested at 250, 500 and 1,000 cycles at low and high temperatures.



Test	Specification	Comment		
Damp Heat	EN60068-2-30 (Db)	Damp heat, Cyclic: Relative humidity: 93-98 % High temperature: +55 °C in 12 hours Low temperature: +25 °C in 12 hours Duration: 21 cycles * 24 hours Actuator is not activated/connected. Tested within 1 hour after condensation, after upper temperature has been reached.		
	EN60068-2-3 (Ca)	Damp heat, Steady state: Relative humidity: 93-95 % Temperature: +40 ± 2 °C Duration: 56 days Actuator is not activated/connected. Tested within one hour after exposure.		
	EN600068-2-78	Temp 40 °C Relative Humidity 95% Test Duration 168 Hours Actuator is not activated/connected. DUT orientation: Normal operating orientation		
Salt Mist	ISO-9227	Continously salt spray test: Salt solution: 5 % sodium chloride (NaCl) Actuator activated/connected. Exposure time: 500 hours		
Degrees of Protection	EN60529 – IP54	IP5X - Dust: Dust-tight, No ingress of dust. Actuator is not connected IPX4 – Water: Ingress of water in quantities causing harmful effects is not allowed. Duration: 100 litres pr. minute in 3 minutes Actuator is not connected		
	EN60529 – IP66	IPX6 –Connected actuator: Actuator is driving out and in for 3 min. 100 (I/min) jet of water is placed at the wiper ring for 3 (min). IPX6 –Connected actuator and push 6800 (N) Actuator is preheated to 85 °C driving out and in for 3 min. and Push 6800 (N) at the end-pos. 100 (I/min.) jet of water (15 °C) is placed at the wiper ring for 3 min.		
	ISO-20653 – IP6KX	Category: 1 (air pressure reduction) Dust medium: Talcum Air pressure: 2 kPa (20 mbar) below normal air pressure Duration: 8 hours.		
	ISO-20653 – IPX9K	High pressure cleaner: Water temperature: +90 °C Water pressure: 350 bar Flowrate: 15L/min Spray angle: 360 ° Spray distance: 200 mm Duration: From any direction continously in 300 seconds Actuator is connected. Ingress of water in quantities causing harmful effects is not allowed.		



Test	Specification	Comment			
	ISO 16750	The actuator has been warmed up to 85 °C for 8 hours. After this it is cooled down in 00 °C salt water. Cooling time: 120 minutes Repeated 5 times and weight recorded after each cycle. Opened for check of residue of salt deposit and water. No weightgain, water or salt residue allowed.			
Chemical test	Chemicals:	Explanation regarding chemical (poss. incl. source of supply and/or trade name):	Test temp °C:	Test duration:	
	Diesel fuel	EN 590	85	22 h	
	'Bio' diesel fuel	EN 14214	85	22 h	
	Engine oil	Multigrade oil SAE OW40, API SL / C	85	22 h	
	Transmission fluid	ATF Dexron III'	85	22 h	
	Hydraulic fluid	DIN 51 524-3 (HVLP ISO VG 46)	85	22 h	
	Grease	DIN 51 502 (KP2K-30)	85	22 h	
	Anti-freeze 50 % (1:1)	Ethylene glycol (C2H602) - Water mixture	85	22 h	
	Urea Nitrogen saturated solution	ISO 22241-1; Urea NOx "ad blue" e.g. P3 Solvclean AK (manufactured by Henkel)	85	22 h	
	Cold cleaner	E.g. P3 Solvclean AK (by Henkel)	RT	22 h	
	Contact spary	E.g. WD 40	85	22 h	
	Ammonium hydroxide	20% diluted water-based solution	RT	22 h	
	Liquid lime 10 % (Super- Cal)	Lime fertiliser, 10% solution; can be obtained from seed and fertiliser traders	RT	22 h	
	NPK Fertilizer (NPK 16-4-12) saturated	Nitrogen (5-9%), phosphorus (5-9%)potassium (5-9%) portions can be obtained from seed and fertiliser traders e.g. COMPO 14361/14354, PhytoGreen NPK 8-8-6 or similar.	RT	22 h	



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