

Actuator LA33

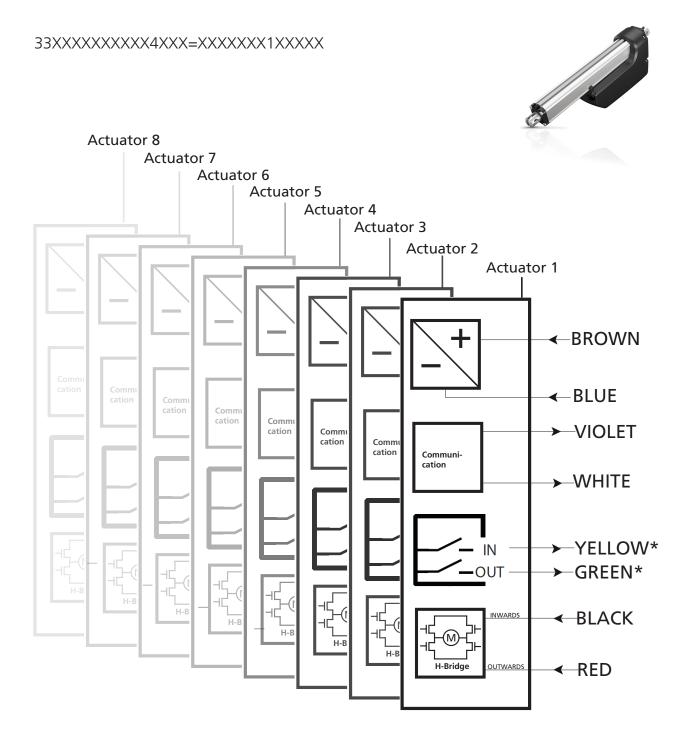
IC Parallel

Connection diagram





Connection diagram





- Please be aware that if the power supply is not properly connected, you might damage the actuator!
- The green and yellow wires from parallel connected actuators must NOT be interconnected

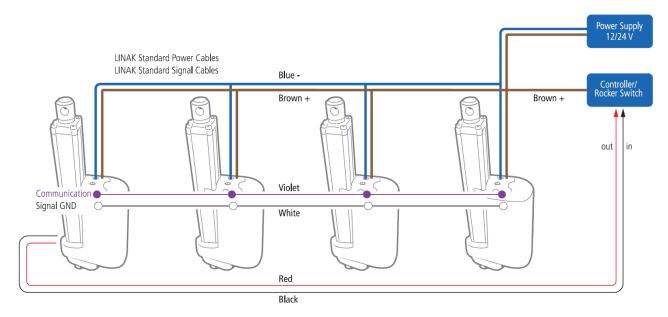
I/O Specifications

Input/Output	Specification	Comments
Description	Parallel drive of up to 8 actuators. A master actuator with an integrated H-bridge controller controls up to 7 slaves. The version with "IC option" cannot be operated with PWM (power supply). See connection diagram, figure above	H-Bridge H-Bridge
Brown	12-24VDC + (VCC) Connect Brown to positive 12V ± 20% 24V ± 10% 12V, max. 13A - current cut off @ 15A 24V, max. 9A - current cut off @10A	Note: Do not change the power supply polarity on the brown and blue wires! The parallel actuators can run on one OR separate power supplies Power supply GND (-) is electrically connected
Blue	12-24VDC - (GND) Connect Blue to negative 12V ± 20% 24V ± 10% 12V, max. 13A - current cut off @ 15A 24V, max. 9A - current cut off @10A	to the housing Current limit levels can be adjusted through BusLink (only one actuator at a time for parallel) If the temperature drops below 0°C, all current limits will automatically increase to 20A for 12V and 15A for 24V
Red	Extends the actuator	On/off voltages: > 67% of V _{IN} = ON < 33% of V _{IN} = OFF Input current: 10mA It does not matter where the in/out signals are applied. You can either choose to connect the signal cable to one actuator OR you can choose to connect the signal cable to each actuator on the line. Either way this will ensure parallel drive
Black	Retracts the actuator	
Green	Endstop signal out	Output voltage min. V _{IN} - 2V Source current max. 100mA Endstop signals are NOT potential free. Endstop
Yellow	Endstop signal in	signals can be configured with BusLink software according to any position needed.
Violet	Parallel communication: Violet cords must be connected together	Standby power consumption: 12V, 85mA 24V, 50mA No feedback available during parallel drive
White	Signal GND: White cords must be connected together	For correct wiring of power GND and Signal GND see next page

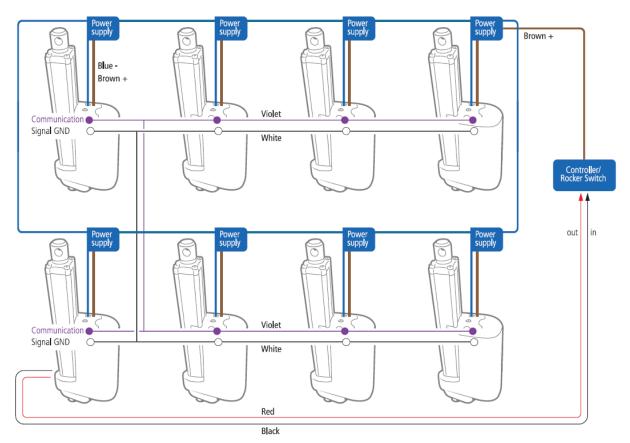


- Current cut-offs should not be used as stop function! This might damage the actuator. Current cut-offs should only be used in emergencies!
- Current cut-off limits are not proportional with the load curves of the actuator. This means that the current cut-offs cannot be used as load indicator.
- There are tolerances on the spindle, nut, gear wheels etc. and these tolerances will have an influence on the current consumption for the specific actuator.

The parallel drive function will support a number of actuators working jointly:



It is both possible to run parallel with a single power supply, or to run each actuator with separate power supplies:



Only standard power and signal cables are available for parallel.

If separate power supplies are used, they must have the same potential, and the power supply GND (blue wires) must be connected in a common ground.

Terms of use

The user is responsible for determining the suitability of LINAK products for specific application. LINAK takes great care in providing accurate and up-to-date information on its products.

However, due to continuous development in order to improve its products, LINAK products are subject to frequent modifications and changes without prior notice. Therefore, LINAK cannot guarantee the correct and actual status of said information on its products.

While LINAK uses its best efforts to fulfil orders, LINAK cannot, for the same reasons as mentioned above, guarantee the availability of any particular product. Therefore, LINAK reserves the right to discontinue the sale of any product displayed on its website or listed in its catalogues or other written material drawn up by LINAK.

All sales are subject to the Standard Terms of Sale and Delivery for LINAK. For a copy hereof, please contact LINAK.